Collective properties of myosin motors and actin filaments

Marbach, Joanny, Kruse, Audoly, Turlier, Ramaswamy, Prost

Molecular motors Molecular motors in cells Two-states models of molecular motors

Collective properties o molecular motors

Spontaneous oscillations of molecular motor

Bidirectional motion of motor assemblies

Parist

Active gel theory

Collective properties of myosin motors and actin filaments

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> Physico-Chimie Curie Institut Curie

GIST Korea, July 2014

MitoSys



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- Cortical actin and dynamics of Cytokinesis
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Organelles and Cytoskeleton

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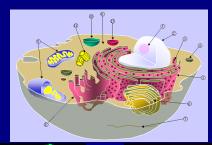
Two-states models of molecular motors

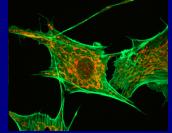
Collective properties o molecular motors

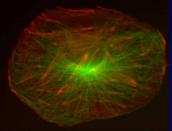
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Molecular motor functions

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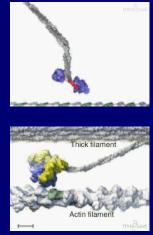
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Motor proteins

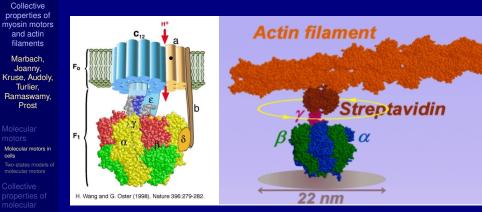
- Muscle contraction (myosin II)
- Cilia and axonemes (Dynein)
- Mitosis
- Intracellular transport
- Inner ear hair cells (Myosin 1c)
- Rotating motors
- Polar filament
- ATP Consumption 25kT

Motor structure



Vale

ATP synthase



Kinosita

Molecular machine regenerating ADP into ATP

Molecular motor functions

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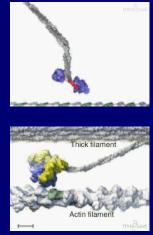
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Motor structure



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Single molecule experiments

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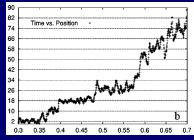
Active gel theory

Processive motors, Bead assays



- Motor unbinding Processivity length $\sim 1 \mu m$
- Stall force 6pN Block
- Velocity 1µm/s

Motor steps



Cappello

- Steps at the period of microtubule
- Existence of backward steps
- Processivity 200 steps

Processivity and motility assays

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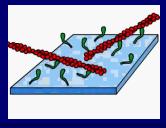
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Motility assay



Processivity

- On and off rates $t_{on} = k_{off}^{-1}$, $t_{off} = k_{on}^{-1}$
- Duty ratio $r = \frac{t_{on}}{t_{on} + t_{off}} = \frac{k_{on}}{k_{on} + k_{off}}$
- Fraction of bound motors r, 1/r motors required on the filament
- Myosin are non-processive r = 0.02. Myosin filaments

Thermodynamics of molecular motors

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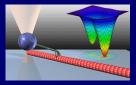
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Linear flux-force relation



- External forces on the motor
 - Mechanical force (optical trap) f
 - Chemical force
 - $\Delta \mu = \mu_{ATP} \mu_{ADP} \mu_{Pi}$
- Flux-force relation
 - $\begin{aligned} \mathbf{v} &= \lambda_{11} \mathbf{f} + \lambda_{12} \Delta \mu \\ \mathbf{r} &= \lambda_{21} \mathbf{f} + \lambda_{22} \Delta \mu \end{aligned}$

- Works as a motor if $f < 0, \Delta \mu > 0$
- Onsager symmetry relations $\lambda_{21} = \lambda_{12}$
- Stall force $f_{s} = -\lambda_{12}\Delta\mu/\lambda_{11}$
- Yield $\eta = -fv/r\Delta\mu$, does not satisfy Carnot's law

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Thermal ratchet motion

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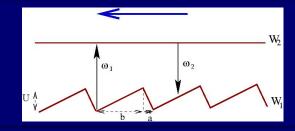
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Periodic potential



Qualitative study

- Efficient motor $a \sim (2D/\omega_2)^{1/2}$
- Gliding velocity $v_g = \frac{1}{\zeta} (\frac{U}{b} f)$
- Average velocity $v = p \frac{a+b}{\omega_2^{-1} + b/v_g}$
- Stall force U = fb or $p \sim 0$

Fokker Planck equation

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Probability conservation

$$\frac{\partial P_1}{\partial t} + \frac{\partial j_1}{\partial x} = -\omega_1(x)P_1 + \omega_2 P_2$$
$$\frac{\partial P_2}{\partial t} + \frac{\partial j_2}{\partial x} = -\omega_2 P_2 + \omega_1(x)P_1$$

Probability fluxes $j_i = -D\left(\frac{\partial P_i}{\partial x} + \frac{P_i}{kT}\frac{\partial W_i}{\partial x} - \frac{P_i}{kT}f\right)$

- No motion at thermal equilibrium
- Non-equilibrium transitions due to ATP consumption
- Advancing velocity

$$v = \left(\int_0^\ell (P_1 + P_2) dx\right)^{-1} \int_0^\ell (j_1 + j_2) dx$$

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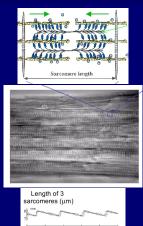
Spontaneous oscillations of molecular motors

Soft Motor model Bidirectional motion

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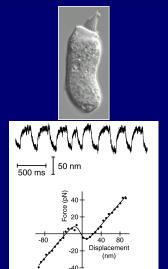
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Heart muscle fiber oscillations Sasaki





Hair cell oscillations Martin



Cochlea

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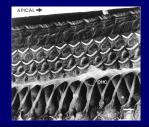
Inner ear and Cochlea





Organ of Corti and hair cells





Hair cells

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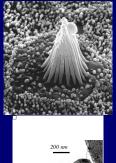
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Stereocilia and tiplinks





Ciliated cells of the inner ear

- Bundle of actin cilia
 - Graded sizes in a bundle
 - Connections via tip-links Hudspeth, Martin
 - Bundles of varying sizes
- Shape and size regulation

Oscillations of molecular motors

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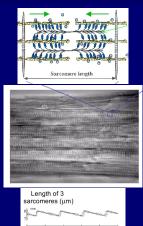
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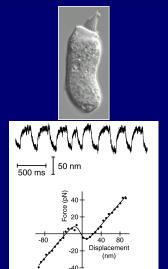
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Heart muscle fiber oscillations Sasaki

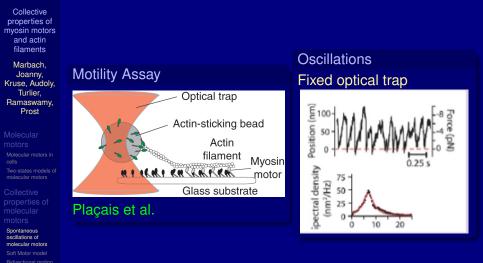




Hair cell oscillations Martin



Biomimetic system



of motor assembli

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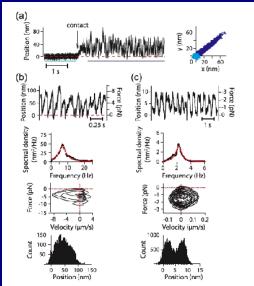
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Two-state model of rigidly bound motors Julicher and Prost

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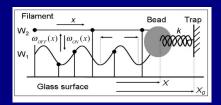
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Trap position X₀ bead position X
Fokker Planck Equation (no thermal noise)

 $\frac{\partial P_1}{\partial t} - \frac{dX}{dt} \frac{\partial P_1}{\partial x} = -\omega_{off}(x)P_1 + \omega_{on}(x)P_2$ $\frac{\partial P_2}{\partial t} - \frac{dX}{dt} \frac{\partial P_2}{\partial x} = -\omega_{on}P_2 + \omega_{off}P_1$

• Random distribution of motors $P_1 + P_2 = 1/\ell$

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Rigid two-state model

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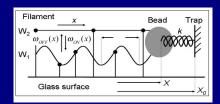
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Force Balance

 $\xi \frac{dX}{dt} = -k(X - X_0) + N \int_0^\ell dx (P_1 \frac{\partial W_1}{\partial x} + P_2 \frac{\partial W_2}{\partial x}) + J(t)$

- Friction force
- Optical trap elastic force
- Motor force
- White noise

Active friction

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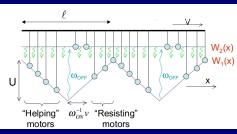
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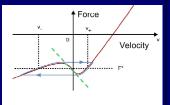
Negative friction



- Motion at constant velocity v
- Motor force

$$F = N \frac{U}{\ell} \frac{v}{\omega_{on}\ell} \sim -\xi_{ac} v$$

Force-velocity relation



- Negative slope at stall force (v = 0) if $-\xi_{ac} > \xi$
- Oscillations

Spontaneous oscillations

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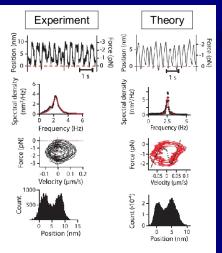
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Oscillations

Oscillations if

 $-\xi_{ac}-\xi \ge k/\omega_{on}$

- Oscillation pulsation at threshold $\Omega = (\omega_{on} k/\xi]^{1/2}$
- Bimodal symmetric oscillations if
 - Weak Noise
 - Close to threshold
- Relaxation oscillations

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Crossbridge models Huxley, Duke, Vilfan

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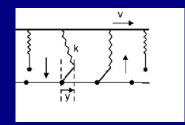
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- No specific adsorption site
- Powerstroke just after attachment
- Load dependent detachment rate
- Oscillations

Soft motor model

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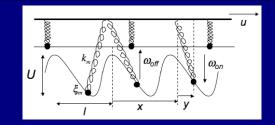
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- Elongation of a motor at time *t* at position *x* attached for a time *τ*, *y*(*x*, *τ*, *t*)
- Force balance

 $\zeta_m(\partial_t y + \partial_\tau y + u(t)(\partial_x y + 1)) = -k_m y - W'(x + y)$

- Probability $p(x, \tau, t)$, $n_d(x, t) + \int_0^\infty d\tau \ p(x, \tau, t) = 1/\ell$
- Probability conservation

 $\partial_t \boldsymbol{\rho} + \partial_\tau \boldsymbol{\rho} + \boldsymbol{u}(t) \partial_x \boldsymbol{\rho} = -\omega_{\text{off}}(x + y, y) \boldsymbol{\rho} + \omega_{\text{on}}(x) \delta(\tau) \boldsymbol{n}_d$

• Motor force $F_m = N k_m \int_0^\infty d\tau \int_0^\ell dx \ y(x, \tau, t) \ p(x, \tau, t)$

Protein friction Sekimoto

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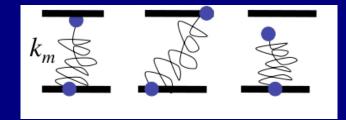
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- Dissipation of spring elastic energy upon detachment
- Protein friction $\xi_{p} = N_{bound} k_{m} / \omega_{off}$
- Number of bond motors $N_{bound} = N\omega_{on}/(\omega_{on} + \omega_{off})$
- Much larger than hydrodynamic friction
- Dominant effect if $\epsilon = \zeta_m / t_m k_m \gg 1$, motor time $t_m \sim \omega^{-1}$
- No dynamic instability if $\epsilon \gg 1$

Equilibrium positions of motors in the potential

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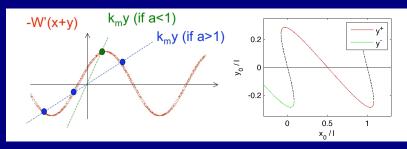
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- Equilibrium positions $0 = -k_m y W'(x + y)$
- Pinning parameter $a = |\min(W''(x)/k_m)| \sim U/(k_m \ell^2)$
- a < 1 one equilibrium position</p>
- a > 1 two equilibrium positions

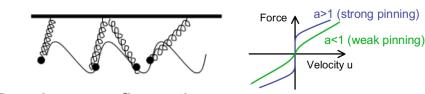
Tomlinson model of solid friction

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Active gel theory



- Continuous force-velocity relation of *a* < 1
- Discontinuity at u = 0 if a > 1 associated to jumps between equilibrium positions
- Solid friction
- No solid friction for the two state model

Adiabatic approximation

Collective properties of myosin motors and actin filaments

Marbach, Joanny, Kruse, Audoly, Turlier, Ramaswamy, Prost

Molecular motors Molecular mot

Two-states models of molecular motors

Collective properties of molecular motors

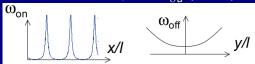
Spontaneous oscillations of molecular motor

Soft Motor model

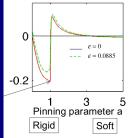
Bidirectional motion of motor assemblies

Active gel theory

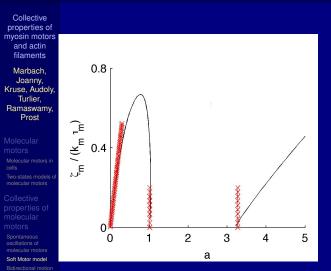
- Limit of low friction $\epsilon \ll 0$
- Steady state for the elongation y
- Effective friction coefficient $\xi_{eff} = -\frac{\partial F_m}{\partial u}(u=0)$



Effective friction coefficient



Stability diagram



- Two instability regions
- Rigid motors
- Soft motors: similar to powerstroke model Vilfan, Duke
- Load dependent detachment rate
- Myosins are soft motors

Outline

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Molecula motors

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- Dynamics of cytokinesis

Bidirectional motion

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Marbach, Joanny, Kruse, Audoly, Turlier, Ramaswamy, Prost

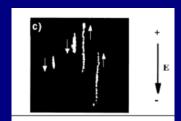
Molecular motors Molecular motors cells Two-states models molecular motors

Collective properties of molecular motors

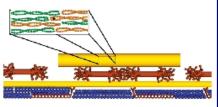
Spontaneous oscillations of molecular motors Soft Motor model

Bidirectional motion of motor assemblies

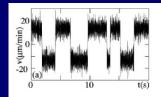
Active gel theory



Riveline et al



Numerical simulations Badoual et al.



- Symmetric filament
- Reversal time proportional to $\exp(N/N_0)$

Gilboa et al

Rigid two-state model

Collective properties of myosin motors and actin filaments

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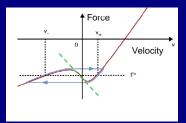
molecular motors

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Active gel theory



- Symmetry breaking: two possible velocities for $N \to \infty$
- Motion reversal for *N* finite due to noise
 - rates $\omega_{on} + \omega_{off} = \omega, \, \omega_{on} = \omega(\eta \alpha \cos \frac{2\pi x}{\ell})$
- η = average fraction of bound motors
- Potential $W(x) = \frac{U}{2}(1 \cos \frac{2\pi x}{\ell})$
- Dynamical phase transition if $\gamma = \frac{\alpha U}{\varepsilon \omega \ell^2} = 1$

First passage time calculation

Collective properties of myosin motors and actin filaments

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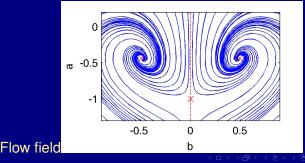
Bidirectional motion of motor assemblies

Active gel theory

• Density of attached motors $\rho(\mathbf{x}) = \eta/\ell + a\cos\frac{2\pi x}{\ell} + b\sin\frac{2\pi x}{\ell}$

- Other Fourier components have negligible contribution
- Fokker Planck Equation $\frac{\partial P}{\partial t} = -\nabla \cdot (\vec{u}P) + \frac{D}{2N} \nabla^2 P$
- Velocity field $u_a = -(a + 1 \gamma b^2)$, $u_b = -(b + \gamma ab)$

• Diffusion constant $D = 4\eta(1 - \eta)/\alpha^2$



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Mechanical analogy Maier and Stein

Collective properties of myosin motors and actin filaments

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Collective properties of molecular motors

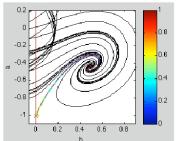
Spontaneous oscillations of molecular motor Soft Motor mode

Bidirectional motion of motor assemblies

Active gel theory No well defined potential (Kramers)WKB Approximation

 $P(a, b, t) = \exp{-NS(a, b, t)}$ $0 = \vec{u} \cdot \nabla S + \frac{D}{2} \nabla S^2$

- S can be considered as an action with the Hamiltonian $H = \vec{u} \cdot \vec{p} + \frac{D}{2}\vec{p}^2$
- Most likely paths are classical trajectories of the Hamiltonian minimizing S



Reversal time calculation

Collective properties of myosin motors and actin filaments

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Molecular motors

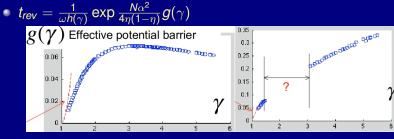
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Bidirectional motion of motor assemblies

Active gel theory Reversal time calculated as the first passage time between the two fixed points



• Bidirectional motions $t_{rev} \sim \exp{\frac{N}{N_0}} \gg \omega$, $N > N_0 \sim 60$

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In vitro active gels, G.Koenderink

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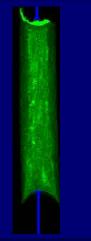
Spontaneous oscillations of molecular motor

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Active gel theory

Actin Myosin gel



Build-up of contractile stress

- Actin-myosin gel in a 400µm diameter capillary
- Accelerated 180 times
- ATP introduced at time *t* = 0. Tensile stress increases with time

Actin gel properties

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Bidirectional motion

Active gel theory

Actin polarization

- Polarization vector
 - Local unitary vector n Unitary vector
 - **p** =< **n** >
 - Nematic or polar ordering
- Conjugate field
 - Free energy change $d\mathcal{F} = -\mathbf{h}d\mathbf{p}$
 - Torque aligning the director $h_{\perp} = K \nabla^2 \phi$
 - Longitudinal field

Maxwell viscoelasticity

- Elastic at short time, viscous at long time
- Single relaxation time τ $\eta = E\tau$
- Constitutive equation

$$\tau \frac{\partial \sigma_{\alpha\beta}}{\partial t} + \sigma_{\alpha\beta} = 2\eta v_{\alpha\beta}$$

 Elastic and viscous stress

Hydrodynamic Theory

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One component effective gel, incompressible

Hydrodynamic Theory

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Soft Motor model

Bidirectional motion of motor assemblies

Active gel theory

- One component effective gel, incompressible
- Linear relations between fluxes and forces

Hydrodynamic Theory

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Active gel theory

- One component effective gel, incompressible
- Linear relations between fluxes and forces
- Description based only on symmetries
 - Polar symmetry: vector **p**, tensor $q_{\alpha\beta} = p_{\alpha}p_{\beta} \frac{1}{3}p^2\delta_{\alpha\beta}$
 - Time reversal symmetry reactive and dissipative components
 - Active effects (motors) described in terms of ATP consumption $\Delta \mu = \mu_{ATP} \mu_{ADP} \mu_P$

Dissipative and reactive fluxes for polar active liquids

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Dissipative fluxes

Onsager relations: crossed terms are equal

$$egin{array}{rcl} \sigma^d_{lphaeta} &=& 2\eta m{v}_{lphaeta} \ P^d_{lpha} &=& rac{h_lpha}{\gamma_1} + \lambda_1 m{p}_lpha \Delta \mu \ r^d &=& \Lambda \Delta \mu + \lambda_1 m{p}_lpha h_a \end{array}$$

Reactive fluxes

Opposite crossed terms. Antisymmetric stress

$$\begin{array}{lll} \sigma^{r}_{\alpha\beta} & = & -\zeta \Delta \mu q_{\alpha\beta} + \frac{\nu_{1}}{2} (p_{\alpha}h_{\beta} + p_{\beta}h_{\alpha} - \frac{2}{3}h_{\gamma}p_{\gamma}\delta_{\alpha\beta}) \\ P^{r}_{\alpha} & = & -\nu_{1}v_{\alpha\beta}p_{\beta} \\ r^{r} & = & \zeta q_{\alpha\beta}v_{\alpha\beta} \end{array}$$

Mechanical stress

Stress equation

Symmetric stres

$$2\eta v_{\alpha\beta} = \left(1 + 1\right)$$

$$\sigma_{\alpha\beta} + \zeta \Delta \mu q_{\alpha\beta} + \tau A_{\alpha\beta} - \frac{\nu_1}{2} (p_\alpha h_\beta + p_\beta h_\alpha - \frac{2}{3} h_\gamma p_\gamma \delta_{\alpha\beta})$$

Antisymmetric stress

$$\sigma^{a}_{lphaeta}=rac{1}{2}(oldsymbol{
ho}_{lpha}oldsymbol{h}_{eta}-oldsymbol{
ho}_{eta}oldsymbol{h}_{lpha})$$

- Convected Maxwell model
- Coupling between stress and polarization
- Active stress
 - myosin coupling to filaments
 - normal stress difference
 - activity coefficient $\zeta < 0$

Bidirectional of motor ass

Two-states models of

Collective

properties of myosin motors and actin filaments Marbach, Joanny, Kruse, Audoly, Turlier, Ramaswamy, Prost

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Collective properties of myosin motors and actin filaments

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Molecula motors

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Cortical actin and dynamics of Cytokinesis

- Acto-Myosin Cortex
- Dynamics of cytokinesis

Spontaneous Frederiks transition

Collective properties of myosin motors and actin filaments

Marbach, Joanny, Kruse, Audoly, Turlier, Ramaswamy, Prost

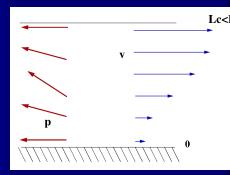
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Active gel theory

Parallel anchoring conditions



Flow bifurcation R.Voituriez

- Same anchoring condition on both surfaces
- Active stress equivalent to an external magnetic field along x axis
- Instability for a finite thickness

$$L_{c} = \left(-\frac{\pi^{2} \mathcal{K}(\frac{4\eta}{\gamma_{1}} + (\nu_{1} + 1)^{2})}{2\tilde{\zeta} \Delta \mu(\nu_{1} + 1)}\right)^{1/2}$$

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Collective properties of myosin motors and actin filaments

Marbach, Joanny, Kruse, Audoly, Turlier, Ramaswamy, Prost

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Collective properties of molecular motors

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Active gel theory

- Tissues
- Bacterial colonies Kessler, Goldstein
- Vibrated granular materials Menon et al.
- Active colloids, Active nematics Ramaswamy et al.
- Bird flocks, Fish shoals Vicsek, Toner, Chaté, Carere



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Constitutive equations of active polar gels

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Cell Cortex

Collective properties of myosin motors and actin filaments

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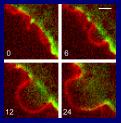
Collective properties o molecular motors

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Active gel theory

Optical Imaging



Charras

- Actomyosin layer
- Polymerization from the surface (formins)
- Treadmilling time \sim 30s

Electron microscopy



Medalia

- Dense actin layer
- Thickness $\sim 1 \mu m$
- Filaments parallel to the cell surface

Cell instabilities associated to cortical layer

Collective properties of myosin motors and actin filaments

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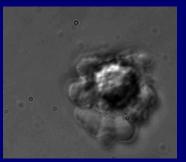
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Active gel theory

Blebs Paluch



- Detachments of the membrane form the cortical layer
 - Bleb lifetime 30s

Cell oscillations Pullarkat



- Oscillations depend on actin contractility
- Oscillations depend on calcium (threshold density)

Multicomponent active gels Callan-Jones and Julicher

Collective properties of myosin motors and actin filaments

Marbach, Joanny, Kruse, Audoly, Turlier, Ramaswamy, Prost

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Collective properties o molecular motors

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Bidirectional motion of motor assemblies

Active gel theory

- Random polarization parallel to the membrane
- Two component system: actin and cytoplasm
- Actin conservation law

$$\partial_t
ho_{g} + \partial_lpha
ho_{g} oldsymbol{v}_{g,lpha} = - oldsymbol{k}_{d}
ho_{g}$$

Boundary condition ρ_gv_{g,z}|_{z=0} = v_ρρ₀
 Constitutive equation, relative flux

$$ho_{g} \left(\mathbf{v}_{lpha} - \mathbf{v}_{g,lpha}
ight) = \chi \left(\partial_{eta} \sigma^{g}_{lpha eta} - \partial_{lpha} \Pi
ight)$$
 $\mathbf{0} = \mathbf{2} \eta \partial_{eta} \mathbf{v}_{g,lpha eta} - \partial_{lpha} \Pi$.

- Effective pressure includes contractile stress of molecular motors Π(ρ) = P(ρ) - ζΔμ
 - Neglect permeation

Active prewetting

Collective properties of myosin motors and actin filaments

Marbach, Joanny, Kruse, Audoly, Turlier, Ramaswamy, Prost

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properties of molecular motors

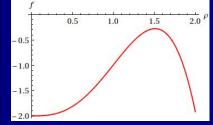
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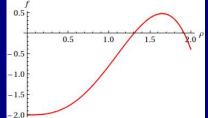
Bidirectional motion of motor assemblies

Active gel theory

One-dimensional geometry

Dynamic equations $\partial_t \rho + \partial_z \rho v = -k_d \rho$ $\eta \partial_z v - \Pi(\rho) = 0$ • Actin velocity $\eta v = \left(\frac{\partial \rho}{\partial z}\right)^{-1} \rho f(\rho)$ $f(\rho) = -k_d \eta - \Pi(\rho)$





No Flux at infinity

3 possible fixed points

Concentration profile in actin layer

Collective properties of myosin motors and actin filaments

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Molecular motors Molecular motors in cells Two-states models of molecular motors

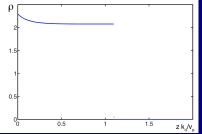
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Active gel theory

- Small activity (Myosin concentration): exponential decay of cencentration
 - Large activity: formation of an active prewetting layer



- Actin cortical layer viewed as a wetting layer
- Almost constant concentration
- Thickness $e \sim v_p/k_d$

Interactions between two cortical layers: capillary condensation

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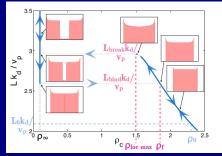
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Active gel theory

- Two layers in close contact
- Existence of metastable states
- Hysteretic phenomena
- Active capillary condensation
- Lamellipodium structure



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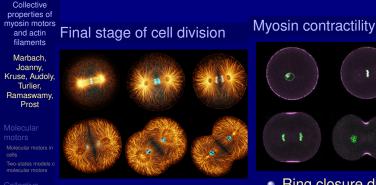
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Cortical actin and dynamics of Cytokinesis Acto-Myosin Cortex

Dynamics of cytokinesis

Final stages of cell division von Dassow



- Collective properties of molecular motors
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Active gel theory

- Separation between daughter cells
- See urchin

- Ring closure due to actin contractility
- Local enhancement of myosin activity due to astral microtubules

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Active gel theory of Cytokinesis

Collective properties of myosin motors and actin filaments

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Molecula motors

Molecular motors in cells

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Active gel theory

- Cytokinesis driven by myosin contractility in the actin cortical layer: cortical flow
- Excess of contractility at the equator of the cell.
- Actin cortical layer described by active gel theory
 - Constant density in cortical layer
 - Ignore polarization effects
 - Viscoelastic actin layer
 - Active stress $\zeta \Delta \mu$ non homogeneous, increases at the equator
- Numerical solution of active gel equations, using Lagrangian coordinates
- Impose cylindrical symmetry of the cell

Dynamics of Cytokinesis

Collective properties of myosin motors and actin filaments

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Molecular motors

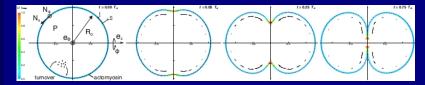
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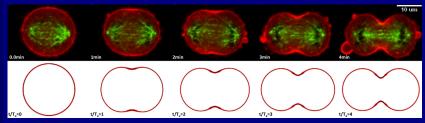
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Active gel theory



Critical value of activity for cytokinesis completion

- Low activity of the ring: cytokinesis failure
- Large activity of the ring: cytokinesis success



Kinetics of ring closure

Collective properties of myosin motors and actin filaments

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Molecular motors Molecular mot

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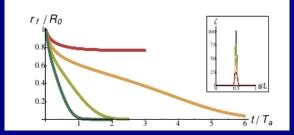
Soft Motor model

Bidirectional motion of motor assemblies

Active gel theory

- Quasi-linear furrow constriction
- Rate of constriction increases with amplitude and width of input signal
- If $w \sim R_0 \frac{dR}{dt} \sim R_0$, Closure time independent of R_0

Good agreement with experiments



Qualitative interpretation

Collective properties of myosin motors and actin filaments

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Molecular motors Molecular moto

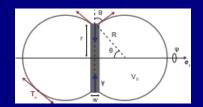
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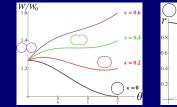
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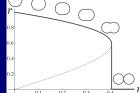
Active gel theory



- Cell tension $T = \frac{e\zeta\Delta\mu}{2}$
- Line tension $\lambda =$
 - $\int ds(T(s)-T_{
 ho})\sim w\delta T$
- Dimensionless number $\kappa \sim \lambda/(2T_{p}R_{0})$

Discontinuous closure transition





 Linear constriction if dissipation dominated by cortical flow

Furrow formation during cytokinesis G.Salbreux

Collective properties of myosin motors and actin filaments

Marbach, Joanny, Kruse, Audoly, Turlier, Ramaswamy, Prost

Molecular motors Molecular motors in cells Two-states models of molecular motors

Collective properties o molecular motors

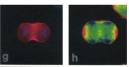
Spontaneous oscillations of molecular motors Soft Mator model

Bidirectional motion of motor assemblies

Active gel theory

Cleavage furrow Y. Wang et

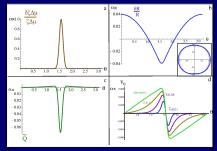






- Enhanced myosin activity at the equator
- Actin flow
- Flow alignment coupling

Active gel theory



C.Elegans embryos S.Grill

Summary

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Moleculaı motors

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Liquid like behavior of tissues Steinberg

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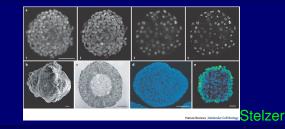
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Isotropic Surface tension of tissues



Stress relaxation by Cell division

- Elastic behavior at short times
- Internal stress due to cell division and apoptosis
- Coupling between cell division and local stress Piel, Bornens
- Tissue viscosity $\eta \sim E/k_d$

Cell division and Homeostatic pressure

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Cell division and apoptosis

- Division rate $k_d(\rho, \text{biochemical state})$
- Apoptosis rate k_a

Tissue Pressure

- Pressure exerted by the cells
- Division rate k_d decreases with pressure
- Apoptosis rate k_a increases with pressure

Homeostatic pressure

Steady state pressure of a tissue P_h

•
$$k_d - k_a(P_h) = 0$$

 $\frac{\partial \rho}{\partial t} + \partial_{\alpha}(\rho \mathbf{V}_{\alpha}) = (\mathbf{k}_{d}(\rho) - \mathbf{k}_{a}(\rho))\rho$

Spheroid growth F.Montel, M.Delarue

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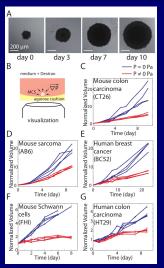
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Growth experiments



Indirect experiments

- Dialysis bag
- Pressure exerted by dextran
- Direct experiments
 - Spheroid in contact with dextran solutions
 - No penetration of dextran in spheroid

Surface growth

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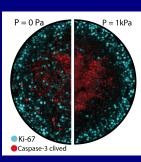
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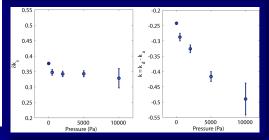
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Pressure dependence



$$\partial_t V = (k_d - k_a)V + 4\pi (\frac{3}{4\pi})^{2/3} \delta k_s \lambda V^{2/3}$$

- Nutrient effect
- Crowding effect
- Negative homeostatic pressure Elgeti

Cell flow

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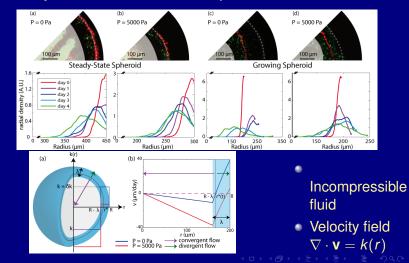
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Injection of fluorescent nano-particles



Particle distribution

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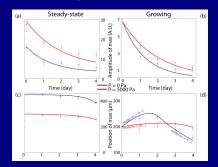
Spontaneous oscillations of molecular motor

Soft Motor model

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Active gel theory

- Transport by cell flow $\partial_t \rho + \nabla v \rho = 0$
- Negligible diffusion
- Density $\rho(r, t) = \rho_0(\tilde{r}, 0) e^{-(k+\delta k)t}$ if $r > R \lambda$ $\tilde{r}^3 = e^{-(k+\delta k)t} r^3 + \int_0^t \delta k (R(t') - \lambda)^3 e^{-(k+\delta k)t'} dt'$



Volume change after a pressure step

Collective properties of myosin motors and actin filaments

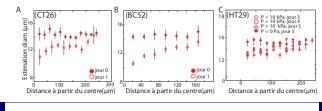
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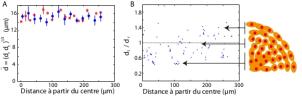
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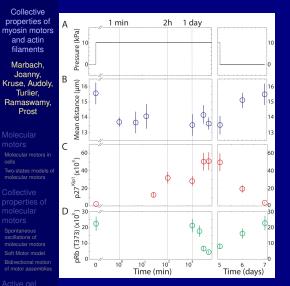
Active gel theory

- Growing spheroid with no applied pressure
- Pressure step 5000 Pa after 4 days
- Volume and anisotropy from correlations between nuclei positions





Volume decrease and cell division



- Decrease in cell division rate, no change in apoptosis
 - Decrease in cell diameter at center after 5 min.
 - P27 Overexpression after 1 day
 - Decrease in cell division after 4 days
 - Cell proliferation arrest in G1 phase

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Isotropic liquid Spheroid

- Constant pressure both in outer dividing layer and in inner layer
- Pressure jump, larger pressure in the outer layer
- Upon pressure jump, cell contraction in the outer layer

Cell orientation

- Viscoelastic spheroid. Elastic short time response
- Active stress because of cell orientation $\sigma^{a}_{\alpha\beta} = \zeta \Delta \mu p_{\alpha} p_{\beta}$
- Active stress depends on pressure
- Alternative: Anisotropic elastic modulus

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