

6-(2) Langevin equation & Brownian motion

$$m \frac{dv}{dt} = \tilde{F}_{\text{ext}} - \alpha v + F'(t)$$

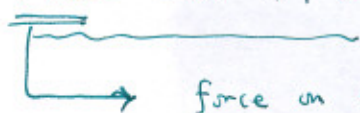
○ Situation: a particle in a liquid (one dimension)

$$\left\{ \begin{array}{l} \text{mass } m \\ \text{center of mass coordinate } x(t) \\ v \equiv \frac{dx(t)}{dt} \end{array} \right.$$

$\equiv$ a particle $\oplus$ heat reservoir

(other molecules in the liquid
and the other degrees of freedom of
the particle)

$$\tilde{F}(t) = -\alpha v + F'(t)$$



force on the center of mass coordinate due to
the interaction between the particle and the reservoir.

$\tilde{F}_{\text{ext}}$: external force

τ' : sufficiently

long
time
scale

$$F(t) = \underbrace{\bar{F}(t)}_{\text{a slowly varying part which leads to the equilibrium situation}} + \underbrace{F'(t)}_{\text{rapidly fluctuating part; purely random}}$$

$\bar{v}$: slowly varying
part

v' : rapidly fluctuating
part

$$\Rightarrow \bar{F}(t) = -\alpha \bar{v} \quad ; \quad v = \bar{v} + v'$$

(Origin: Consider the situation of $\tilde{F}_{\text{ext}} = 0$.

And $\bar{v} \neq 0$ initially.

To achieve exponentially rapid decay to $\bar{v}_{\text{eq}} = 0$,
one can have $m \frac{d\bar{v}}{dt} = -\alpha \bar{v}$.) equilibrium value.

$$\bar{F}(t) = -\alpha \bar{v} \sim \text{frictional force.}$$

$\alpha \sim$ frictional constant

$\Rightarrow$ energy dissipation to environment

Show
the
schematic
diagram
of
 $F(t)$

 τ^*
correlation time

① Example: calculation of the mean-square displacement $\langle x^2 \rangle$

put $F_{ext} = 0$.

initial condition: $x=0$ at $t=0$.

$$m \frac{dV}{dt} = -\alpha V + F'(t)$$

in a time interval $\neq t$

(sufficiently long
time scale)

$$\Rightarrow m \kappa \frac{d\dot{x}}{dt} = -\alpha x \dot{x} + x F'(t)$$

$$\vec{v} = \vec{v}(0) e^{-\frac{\alpha}{m} t} = \vec{v}(0) e^{-t/\tau_{\text{relax}}}$$

$$\tau_{\text{relax}} = m/\alpha$$

$\langle \dots \rangle$ ensemble average.

$$\Rightarrow \left\langle m \frac{d(x\dot{x})}{dt} - m \dot{x}^2 = -\alpha x \dot{x} \right\rangle \quad (\because \langle x F' \rangle = \langle x \rangle \langle F' \rangle = 0 \cdot \underline{\quad} = 0)$$

$$\text{use } \frac{1}{2} m \langle \dot{x}^2 \rangle = \frac{1}{2} kT$$

$$\Rightarrow m \left\langle \frac{d}{dt} (x\dot{x}) \right\rangle = m \frac{d}{dt} \langle x\dot{x} \rangle = kT - \alpha \langle x\dot{x} \rangle$$

(see Reif, p. 566)

$$\Rightarrow \langle x\dot{x} \rangle = C e^{-\gamma t} + \frac{kT}{\alpha}, \quad \gamma \equiv \frac{\alpha}{m}$$

since $x=0$ at $t=0$, $C = -kT/\alpha$.

$$\Rightarrow \langle x\dot{x} \rangle = \frac{kT}{\alpha} (1 - e^{-\gamma t})$$

$$\Rightarrow = \frac{1}{2} \frac{d\langle x^2 \rangle}{dt}$$

$$\langle x^2 \rangle = \frac{2kT}{\alpha} \left(t - \frac{1}{\gamma} (1 - e^{-\gamma t}) \right)$$

Study limiting cases:

$$t \ll \gamma^{-1} \Rightarrow e^{-\gamma t} = 1 - \gamma t + \frac{1}{2} \gamma^2 t^2 - \dots$$

$$\Rightarrow \langle x^2 \rangle = \frac{kT}{m} t^2 \quad \sim \text{free particle}$$

moving (without

interaction with environment)

$$t \gg \gamma^{-1} \Rightarrow \langle x^2 \rangle = \frac{2kT}{\alpha} t$$

$\sim$ diffusion; random walk.

$$\Rightarrow \langle x^2 \rangle = 2Dt$$

$$D = \frac{kT}{\alpha} = \frac{kT}{m} \tau_{\text{relax}} = \frac{1}{3} m \bar{v}^2 \cdot \frac{1}{m} \tau_{\text{relax}} = \frac{1}{3} \bar{v}^2 \tau_{\text{relax}} \approx \frac{1}{3} \bar{v} \lambda$$

Now, turn on $F_{ext} = eE$. (electric field)

$$m \frac{dv}{dt} = eE - \alpha v + F'(t)$$

at $t \rightarrow \infty$ (steady-state situation)

$$eE - \alpha \bar{v} = 0 \quad (\because \frac{d\bar{v}}{dt} = 0)$$

$$\text{mobility} \equiv \mu \equiv \bar{v}/E = e/\alpha$$

$$\mu/D = e/\alpha \cdot \left(\frac{kT}{\alpha}\right)^{-1} = \frac{e}{kT}$$

$\sim$ Einstein relation

② Relation between α and the fluctuating force

$$m \frac{dv}{dt} = F_{\text{ext}} + \underline{F}$$

it comes from the interaction between the particle and heat reservoir. (see Ref Fig. 15.5.1)

at time interval τ :

$\tau \gg \tau^*$; $\tau^* \sim$ correlation time which is of the order of the mean period of fluctuations of the force $F(t)$.
In $[t, t+\tau]$, the variation of F_{ext} can be negligible.

$\tau \sim$ macroscopically short so that F_{ext} does not vary over τ ,
but microscopically long

$$\Rightarrow m \langle v(t+\tau) - v(t) \rangle = F_{\text{ext}} \tau + \int_t^{t+\tau} \langle F(t') \rangle dt'$$

↑
ensemble average

Let's focus on $\langle F(t') \rangle$.

① In equilibrium, $\langle F(t') \rangle_0 = 0$

($\langle \dots \rangle_0$ means the ensemble average in equilibrium.)

$\sim$ trivial. (consider $F_{\text{ext}}=0$ case. $\Rightarrow \langle v(t+\tau) \rangle = \langle v(t) \rangle$ in equilibrium.)

② $\langle F \rangle$ is affected by the motion of ^{the} particle.

($\because$ ~~the environment~~ The internal equilibrium of environment (heat reservoir) is ~~disturbed~~ disturbed as the velocity of particle changes.)

$$\Rightarrow \langle F(t') \rangle \approx -\beta \bar{v}(t) \int_t^{t'} dt'' \langle F(t') F(t'') \rangle, \quad t' = t + \tau' \\ \tau' \gg \tau^*$$

derivation

At some time t ,

the particle has ~~an~~ velocity $v(t)$

$W_r(t)$: the probability that the particle (its center-of-mass coordinate) is in state r .

Approximation: $W_r(t) \rightarrow W_r^{(0)}$ equilibrium probability.

(i) We consider the situation where the system is very close to its equilibrium.

Or

(ii) The system is in equilibrium at t .

After τ' , it deviates from the equilibrium spontaneously.

At later time $t' = t + \tau'$ ($\tau' \gg \tau^*$),

$$v(t + \tau') = v(t) + \Delta v(\tau')$$

$$E' \text{ (energy of environment) at } t' = E'(t) + \Delta E'(\tau')$$

$$\langle F(t') \rangle = \sum_r W_r(t + \tau') F_r(t')$$

$$W_r(t + \tau') \approx W_r(t) \frac{\Omega(E' + \Delta E') \cdot 1}{\Omega(E') \cdot 1} = e^{\beta \Delta E'} W_r(t)$$

$$\approx (1 + \beta \Delta E') W_r(t) \quad \left(\tau' \sim \text{small enough} \right) \quad \left[\beta = \frac{\partial \ln \Omega(E')}{\partial E'} \right]$$

$$\rightarrow (1 + \beta \Delta E') W_r^{(0)} \quad (\text{approximation})$$

$$\Rightarrow \langle F(t') \rangle = \sum_r W_r^{(0)} F_r(t') (1 + \beta \Delta E')$$

$$= \langle F(t') (1 + \beta \Delta E') \rangle_0$$

$$= \langle \beta \Delta E' F(t') \rangle_0$$

$$\langle \dots \rangle_0$$

$\sim$ ensemble average
in equilibrium.

$$\Delta E' = - \int_t^{t'} \underbrace{v(t'') F(t'')}_{\text{work done by } F \text{ on the system}} dt'' \approx -v(t) \int_t^{t'} F(t'') dt''$$

work done by F on the system

$\leftarrow$ variation of $v(t)$ is neglected,
($\tau' \sim$ small enough)

$$\Rightarrow \langle F(t') \rangle = -\beta \langle v(t) \int_t^{t'} F(t') F(t'') dt'' \rangle_0$$

$$\approx -\beta \bar{v}(t) \int_t^{t'} \langle F(t') F(t'') \rangle_0 dt''$$

$$\Rightarrow \frac{m \langle v(t+\tau) - v(t) \rangle}{\tau} = \bar{F}_{\text{ext}}(t) - \beta \bar{v}(t) \int_t^{t+\tau} dt' \int_t^{t'} dt'' \langle F(t') F(t'') \rangle_0$$

0 Correlation function

$$K(s) \equiv \overline{\langle F(t') F(t'+s) \rangle_0}$$

ensemble average taken in equilibrium.

$\Rightarrow K(s) \sim$ independent of t' .

general
properties:

$$① K(0) = \langle F(t) F(t) \rangle > 0.$$

$$② s \gg \tau^*, K(s) \rightarrow \langle F(t) \rangle \langle F(t+s) \rangle$$

$$\Rightarrow K(s) \rightarrow 0 \text{ if } \langle F(t) \rangle = 0.$$

$$③ |K(s)| \leq K(0)$$

proof $\langle [F(t) \pm F(t+s)]^2 \rangle \geq 0$

$$\Rightarrow 2(K(0) \pm K(s)) \geq 0$$

$$\Rightarrow -K(0) \leq K(s) \leq K(0)$$

$$④ K(s) = K(-s)$$

$$\begin{aligned} \text{proof } K(s) &= \langle F(t) F(t+s) \rangle = \langle F(t-s) F(t) \rangle = \langle F(t) F(t-s) \rangle \\ &= K(-s) \end{aligned}$$

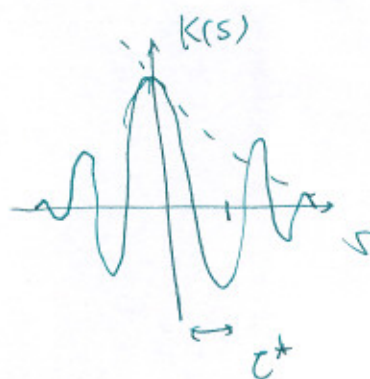
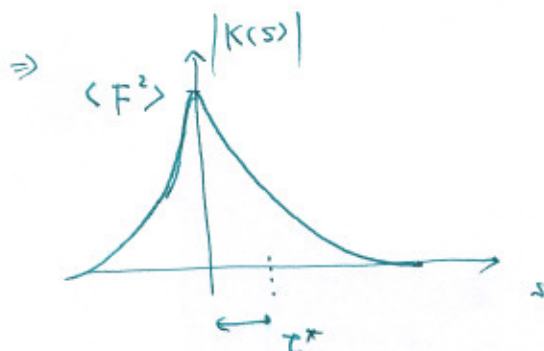
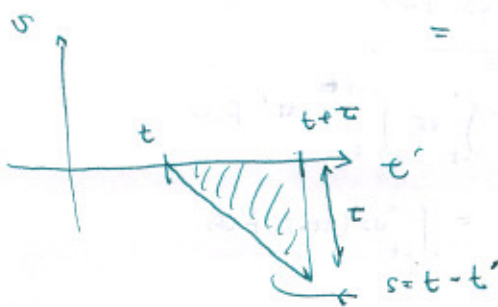


Fig: schematic shapes of $K(s)$

$$\Rightarrow \int_t^{t+\tau} dt' \int_{t-t'}^0 ds K(s) = \int_{-\tau}^0 ds \int_{t-s}^{t+\tau} dt' K(s)$$



$$= \int_{-\tau}^0 ds K(s) (\tau + s)$$

$$\approx \int_{-\tau}^0 ds \tau K(s)$$

($\because K(s) \neq 0$ only for $s \lesssim \tau^*$

($\tau \gg \tau^*$.)

$$\approx \tau \int_{-\infty}^0 ds K(s)$$

$$= \frac{1}{2} \tau \int_{-\infty}^{\infty} ds K(s)$$

$$\Rightarrow m \langle v(t+\tau) - v(t) \rangle = \tilde{F}_{\text{ext}}(t) \tau - \alpha \bar{v}(t) \tau,$$

$$\alpha \equiv \frac{1}{2kT} \int_{-\infty}^{\infty} \langle F(0) F(s) \rangle_0 ds$$

Note: $\frac{d\bar{v}}{dt} = \frac{m \langle v(t+\tau) - v(t) \rangle}{\tau}$

($\because \langle v \rangle$ varies very slowly.

$\bar{v}$ not changed over τ .)

$$\Rightarrow \frac{d\bar{v}}{dt} = \tilde{F}_{\text{ext}} - \alpha \bar{v}$$

if $F_{\text{ext}} = 0$, $\bar{v}(t) = \bar{v}(0) e^{-\gamma t}$

Since $\langle v \rangle$ varies slowly, $\left| \left(\frac{d\bar{v}}{dt} \right) \tau \right| \ll \bar{v}$

$$\Rightarrow \gamma \tau \ll 1 \Rightarrow \gamma^{-1} \gg \tau \gg \tau^*$$

*

fluctuation - dissipation theorem

$$\alpha = \frac{1}{2kT} \int_{-\infty}^{\infty} \langle F(0) F(s) \rangle_0 ds$$

dissipation

correlation of fluctuating force in equilibrium

Interaction between the system and the reservoir is ~~large~~ stronger

$\Rightarrow$ F_{fl} must be larger

α is larger since the system goes to equilibrium more rapidly.

② Example of fluctuation-dissipation theorem.

electrical circuit:

$$L \frac{dI}{dt} = -RI + \underbrace{V(t)}_{\text{fluctuating voltage}}; \langle V(t) \rangle = 0, \quad \langle \frac{1}{2} L I^2 \rangle = \frac{1}{2} kT. \\ (\text{see Reif p. 590})$$

$$\updownarrow \\ m \frac{dv}{dt} = -\alpha v + F'(t), \quad \langle \frac{1}{2} m v^2 \rangle = \frac{1}{2} kT$$

$\Rightarrow$ One can immediately know the correspondence between them.

$$\rightarrow R = \frac{1}{2kT} \int_{-\infty}^{\infty} \langle V(s) \cdot V(s) \rangle ds \quad \text{see}$$

$$\downarrow \\ \frac{1}{R} = \frac{1}{2kT} \int_{-\infty}^{\infty} \langle I(s) \cdot I(s) \rangle ds$$

Generalization:

$\Rightarrow$

Kubo formula

$$\underbrace{j_x}_{\text{conductivity}} = \frac{J_x}{E} = \frac{1}{2kT} \int_{-\infty}^{\infty} \langle j_x(s) j_x(s) \rangle ds$$

3 Velocity correlation function and mean-square displacement (skipped)

Goal: to calculate $\langle x^2(t) \rangle$.

$$x(0) = 0 \quad \text{at } t=0.$$

$$x(t) = \int_0^t v(t') dt'$$

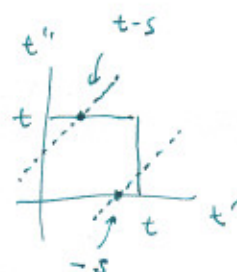
$$\Rightarrow \langle x^2(t) \rangle = \int_0^t dt' \int_0^t dt'' \langle v(t') v(t'') \rangle$$

$$= \int_0^t dt' \int_0^{t-t'} dt'' \langle v(0) v(t''-t') \rangle$$

$$= \int_0^t ds \int_0^{t-s} dt' K_v(s) + \int_{-t}^0 ds \int_{-s}^t dt' K_v(s)$$

$$= \int_0^t ds K_v(s) (t-s) + \int_{-t}^0 ds K_v(s) (t+s)$$

$$= 2 \int_0^t ds K_v(s) (t-s)$$



$$\downarrow s = t'' - t'$$

$$K_v(s) = \langle v(0) v(s) \rangle$$

$$\downarrow s \rightarrow -s$$

$$m \frac{dv}{dt} = -\gamma v + F'(t)$$

$$\rightarrow v(s+\tau) - v(s) = -\gamma v(s) \tau + \frac{1}{m} \int_s^{s+\tau} F'(t') dt' \quad (\gamma = \alpha/m, \tau \gg \tau^*)$$

$$\rightarrow \langle v(0) v(s+\tau) \rangle - \langle v(0) v(s) \rangle = -\gamma \tau \langle v(0) v(s) \rangle + \frac{1}{m} \langle v(0) \int_s^{s+\tau} F'(t') dt' \rangle$$

$$\Rightarrow \frac{d}{ds} \langle v(0) v(s) \rangle = -\gamma \langle v(0) v(s) \rangle \quad \approx \frac{1}{m} \langle v(0) \rangle \langle \int_s^{s+\tau} F'(t') dt' \rangle = 0$$

$$\Rightarrow K_v(s) = \langle v^2(0) \rangle e^{-\gamma s} \quad \text{for } s > 0.$$

$$\Rightarrow K_v(s) = \langle v^2(0) \rangle e^{-\gamma |s|} \quad (\because K_v(s) = K_v(-s))$$

$$\Rightarrow \langle x^2(t) \rangle = \frac{2kT}{m} \int_0^t ds (t-s) e^{-\gamma |s|} \quad (\because \frac{1}{2} m v^2(0) = \frac{1}{2} kT)$$

$$= \frac{2kT}{m \gamma} \left(t - \frac{1}{\gamma} (1 - e^{-\gamma t}) \right)$$

(the same result with the previous calculation, see the note around Einstein relation.)

① generalization of fluctuation-dissipation theorem

Consider an isolated system which has a parameter set $\{y_1, \dots, y_n\}$

$$\Rightarrow \begin{cases} \# \text{ of accessible state } \Omega = \Omega(y_1, y_2, \dots, y_n) \\ \text{Entropy } S = k \ln \Omega \end{cases}$$

$$\left(\begin{array}{l} \text{At equilibrium : } y_i = \tilde{y}_i, \quad \left. \frac{\partial S}{\partial y_i} \right|_{y=\tilde{y}} = 0 \quad \text{for all } i. \end{array} \right.$$

$$\begin{aligned} \text{Near equilibrium : } S(\{y_i\}) &= S(\tilde{y}_1, \dots, \tilde{y}_n) + \frac{1}{2} \sum_{i,k} C_{ik} (y_i - \tilde{y}_i) (y_k - \tilde{y}_k) \\ C_{ik} &= C_{ki} = \frac{\partial^2 S}{\partial y_i \partial y_k} \end{aligned}$$

Now, consider the time dependence of $\dot{y}_i = \frac{dy_i}{dt}$ and $\partial S / \partial y_i$
typically, $\dot{y}_i, \frac{\partial S}{\partial y_i} \sim$ rapidly fluctuating

with correlation time τ^*

$$\left(\begin{array}{l} \text{at equilibrium, } \overline{\frac{\partial S}{\partial y_i}} = 0 \quad \text{and} \quad \frac{d\tilde{y}_i}{dt} = 0 \quad \text{for all } i. \\ \text{in nonequilibrium, } \frac{d\bar{y}_i}{dt} = \sum_{j=1}^n \alpha_{ij} \bar{Y}_j \\ \text{(near equilibrium)} \end{array} \right.$$

$$\left(\begin{array}{l} \alpha_{ij} \sim \text{friction coefficient} \\ \bar{Y}_j = \frac{\partial S}{\partial y_j} = \sum_k C_{jk} (\bar{y}_k - \tilde{y}_k) \\ \sim \text{"driving force"} \end{array} \right.$$

This equation is similar to (cf. generalized force $= \frac{1}{\beta} \frac{\partial \ln \Omega}{\partial y}$)
~~the~~ Langevin eq. without F_{ext} .

$$\Rightarrow \alpha_{ij} = \frac{1}{k} \int_{-\infty}^0 ds K_{ij}(s)$$

$$K_{ij}(s) \equiv \langle \dot{y}_i(t) \dot{y}_j(t+s) \rangle_0 = \langle \dot{y}_i(0) \dot{y}_j(s) \rangle_0$$

$\sim$ general form of the fluctuation-dissipation theorem

Generalized derivation of fluctuation-dissipation theorem

$\tau \gg \tau^*$, but $\tau \sim$ macroscopically short time interval

"Coarse-grained" time derivative of $\langle y_i \rangle$

$$\frac{1}{\tau} \langle y_i(t+\tau) - y_i(t) \rangle = \frac{1}{\tau} \int_t^{t+\tau} \langle \dot{y}_i(t') \rangle dt'$$

At time t , as an approximation, the system is assumed to be

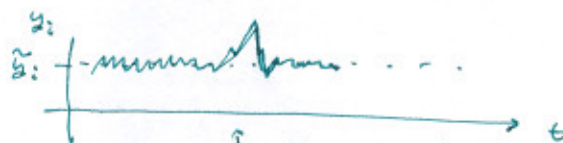
in equilibrium.

$$\Rightarrow \langle \dot{y}_i(t) \rangle = 0$$

We ^{are} considering the system near equilibrium.

or,

We can imagine spontaneous deviation from equilibrium at $t+\tau'$.



After τ' ($\tau' > \tau^*$),

the parameters are assumed to change

from $y_i(t)$ to $y_i(t+\tau') = y_i(t) + \Delta y_i(\tau')$ by small $\Delta y_i(\tau')$.

$\Rightarrow$ This causes entropy change $\Delta S(\tau')$.

$$\langle \dot{y}_i(t') \rangle = \sum_r W_r(t+\tau') (\dot{y}_i)_r$$

($t' = t+\tau$)

$W_r(t+\tau')$ probability that the system is at state r .

$(\dot{y}_i)_r \sim$ expectation value of $\dot{y}_i$ when the system is at state r .

$$\frac{W_r(t+\tau')}{W_r(t)} = \frac{\Omega(t+\tau')}{\Omega(t)} = e^{\Delta S(\tau')/k} \approx 1 + \Delta S(\tau')/k.$$

($\because \tau'$ is small enough.)

$$\Rightarrow \langle \dot{y}_i(t') \rangle = \sum_r W_r(t) (1 + \Delta S/k) (\dot{y}_i)_r$$

$$= \langle \dot{y}_i [1 + \frac{1}{k} \Delta S(\tau')] \rangle_0$$

$$= \frac{1}{k} \langle \dot{y}_i(t') \Delta S(\tau') \rangle_0$$

$$\Delta S(\tau') = \sum_j \frac{\partial S}{\partial y_j} \Delta y_j(\tau')$$

$\langle \dots \rangle_0 \sim$ ensemble average in equilibrium.

($\because$ at t , the system is in equilibrium.)

⇒

$$\begin{aligned}
 \langle y_i(t+\tau) - y_i(t) \rangle &= \frac{1}{k} \int_t^{t+\tau} \langle \dot{y}_i(t') \Delta S(t'-t) \rangle_0 dt' \\
 &= \frac{1}{k} \int_t^{t+\tau} \langle \dot{y}_i(t') \sum_j \frac{\partial S}{\partial y_j} \Delta y_j(t'-t) \rangle_0 dt' \\
 &= \frac{1}{k} \sum_j \int_t^{t+\tau} dt' \langle \dot{y}_i(t') \bar{Y}_j(t) \int_t^{t'} dt'' \dot{y}_j(t'') \rangle_0 \\
 &\approx \frac{1}{k} \sum_j \bar{Y}_j(t) \int_t^{t+\tau} dt' \int_t^{t'} dt'' \langle \dot{y}_i(t') \dot{y}_j(t'') \rangle_0
 \end{aligned}$$

$$S \equiv t'' - t', \quad K_{ij}(s) \equiv \langle \dot{y}_i(t) \dot{y}_j(t+s) \rangle_0$$

$$\begin{aligned}
 \Rightarrow \langle y_i(t+\tau) - y_i(t) \rangle &= \frac{1}{k} \sum_j \bar{Y}_j(t) \int_{-\tau}^0 ds \int_{t-s}^{t+\tau} dt' K_{ij}(s) \\
 &= \frac{1}{k} \sum_j \bar{Y}_j \tau \int_{-\infty}^0 ds K_{ij}(s) \\
 &= \sum_j \alpha_{ij} \bar{Y}_j
 \end{aligned}$$

$$\Rightarrow \alpha_{ij} = \frac{1}{k} \int_{-\infty}^0 ds K_{ij}(s)$$

○ Onsager relations

In equilibrium, $K_{ij}(s) = \langle \dot{y}_i(t) \dot{y}_j(t+s) \rangle_0$

$\sim$ independent of t .

$$K_{ij}(s) = \langle \dot{y}_i(t) \dot{y}_j(t+s) \rangle_0$$

$$= \langle \dot{y}_i(t-s) \dot{y}_j(t) \rangle_0$$

$$= \langle \dot{y}_j(t) \dot{y}_i(t-s) \rangle_0$$

$$= K_{ji}(-s)$$

time reversal : $t \rightarrow -t$; in the presence of external magnetic field $\vec{B}$
 symmetry
 Then, the direction of magnetic field is reversed as $t \rightarrow -t$;

$$\vec{B} \rightarrow -\vec{B}$$

($\because$ Current which produces $\vec{B}$ becomes to have the reverse direction)

$$K_{ij}(s; \vec{B}) \rightarrow K_{ji}^+(s; -\vec{B})$$

(~~double~~ $+$: it represents the change of sign of $(\dot{y}_i(t) \dot{y}_j(t+s))$ under the time reversal.)

$$(\because K_{ij}(s; \vec{B}) \rightarrow K_{ji}^+(-s; -\vec{B}) = K_{ji}^+(s; -\vec{B}))$$

$\Rightarrow$ Onsager relation. (or Onsager reciprocal symmetry)

Example: $y_i, y_j \sim$ both displacements or both velocities.

①

$$\Rightarrow \dot{y}_i \dot{y}_j \rightarrow \dot{y}_i \dot{y}_j \text{ under time reversal}$$

(no change of sign)

$$\Rightarrow K_{ij}(s; \vec{B}) = K_{ji}(s; -\vec{B})$$

$$\Rightarrow \alpha_{ij}(\vec{B}) = \alpha_{ji}(-\vec{B})$$

② $y_i \rightarrow$ displacement, $y_j \sim$ velocity.

$$\Rightarrow \dot{y}_i y_j \rightarrow -\dot{y}_i y_j \text{ under time reversal}$$

$$\Rightarrow K_{ij}(s; \vec{B}) = -K_{ji}(s; -\vec{B}), \quad \alpha_{ij}(\vec{B}) = -\alpha_{ji}(-\vec{B})$$