

# The relative isoperimetric inequality in Cartan-Hadamard 3-manifolds

*To the memory of José F. Escobar*

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**Abstract.** We prove that a region  $D$  outside a convex set  $C$  with smooth boundary in a three-dimensional Cartan-Hadamard manifold  $M$  satisfies the relative isoperimetric inequality  $\text{area}(\partial D \sim \partial C)^3 \geq 18\pi \text{vol}(D)^2$ , with equality if and only if  $D$  is isometric to a Euclidean half ball. We also prove similar sharp inequalities when the sectional curvature of  $M$  is bounded above by a negative constant.

## 1. Introduction

Let  $\mathbb{H} := \{(x_1, \dots, x_n) \in \mathbb{R}^n : x_n \geq 0\}$  be the closed upper half space of  $\mathbb{R}^n$ . Given a set  $D \subset \mathbb{H}$ , let  $D' \subset \mathbb{R}^n \sim \mathbb{H}$  be the mirror image of  $D$  across  $\partial\mathbb{H}$ , where  $\sim$  denotes the set exclusion operator. Then the classical isoperimetric inequality implies that

$$\text{area}(\partial(D \cup D'))^n \geq n^n \omega_n \text{vol}(D \cup D')^{n-1},$$

with equality if and only if  $D \cup D'$  is a ball. Here  $\omega_n$  denotes the volume of the unit ball in  $\mathbb{R}^n$ , and  $\text{area}$  and  $\text{vol}$ , respectively, the  $(n-1)$  and  $n$  dimensional Hausdorff measures. As a result one gets

$$(1.1) \quad \text{area}(\partial D \sim \partial\mathbb{H})^n \geq \frac{1}{2} n^n \omega_n \text{vol}(D)^{n-1},$$

with equality if and only if  $D$  is a half ball and  $\partial D$  meets  $\partial\mathbb{H}$  in an orthogonal way.

This proposes the following interesting problems: Given a set  $D$  outside a convex set  $C$  in  $\mathbb{R}^n$ , does  $D$  satisfy inequality (1.1)? Does equality hold if and only if  $D$  is a half ball? Is inequality (1.1) still true outside a convex set in a Cartan-Hadamard manifold?

Inequality (1.1) will be called the *relative isoperimetric inequality* for  $D$ . The proof of (1.1) in  $\mathbb{R}^2$  is easy once one reflects the convex hull of  $D$  about its linear boundary. For  $\mathbb{R}^n$ ,  $n \geq 3$ , some partial results have been obtained in [K], [C1]. I. Kim [K] proved (1.1) for the epigraph of a  $C^2$  convex function and the first-named author [C1] proved the relative isoperimetric inequality when  $\partial D \cap \partial C$  is a graph which is symmetric about  $(n - 1)$  hyperplanes of  $\mathbb{R}^n$ .

In this paper we prove that the relative isoperimetric inequality (1.1) holds outside a closed convex set  $C$  with smooth boundary in a three-dimensional Cartan-Hadamard manifold  $M$ . More precisely, let  $C$  be a closed convex set with interior points in a Cartan-Hadamard manifold  $M^3$  with sectional curvatures bounded above by a nonpositive constant  $\kappa$ . Let us denote by  $M(\kappa)$  the three-dimensional simply connected space form with sectional curvature  $\kappa$  (Euclidean space for  $\kappa = 0$  or hyperbolic space of sectional curvatures equal to  $\kappa$  otherwise), then we prove in Theorem 3.2 that, for any bounded set  $D \subset M^3 \sim C$  with piecewise smooth boundary, we have

$$(1.2) \quad \text{area}(\partial D \sim \partial C) \geq \frac{1}{2} \text{area}(\partial B),$$

where  $B$  is a geodesic ball in  $M(\kappa)$  with  $\text{vol}(B) = 2 \text{vol}(D)$ , and  $\text{area}$  is the 2 dimensional Hausdorff measure. Moreover, we show that equality holds in (1.2) if and only if  $D$  is isometric to a half ball in  $M(\kappa)$ .

The two-dimensional relative isoperimetric problem (1.2) was solved affirmatively in [C1]. The four-dimensional relative isoperimetric inequality (1.1) was obtained in [C2] following C. Croke [Cr].

Our proof for the three-dimensional case follows the scheme of B. Kleiner [K1]: the isoperimetric inequality we intend to prove is equivalent to the comparison  $I_C \geq I_{\mathbb{H}}$  of the isoperimetric profiles  $I_C$  of  $M \sim C$  and  $I_{\mathbb{H}}$  of the complement of a closed half space  $\mathbb{H} \subset M(\kappa)$ . When an isoperimetric region  $\Omega_0$  of volume  $v_0$  exists in  $M \sim C$  and the profile  $I_C$  is smooth at  $v_0$  then the derivative  $I'_C(v_0)$  is equal to the constant mean curvature of the boundary  $\partial\Omega_0 \sim \partial C$ . Hence, in order to compare  $I_C$  and  $I_{\mathbb{H}}$  we only need to compare their derivatives, that is, the mean curvatures of isoperimetric regions in both spaces for given volumes. Since both  $I_C$  and  $I_{\mathbb{H}}$  are increasing functions, we only need to make this comparison for given areas. A main problem for this approach is that isoperimetric regions need not exist in the noncompact manifold  $M \sim C$  but, as in [K1], we avoid it by considering an exhaustion of  $M \sim C$  by relatively compact sets where isoperimetric regions can be found. The mean curvature comparison is obtained in Proposition 3.1 by techniques similar to the ones used in [R], which are inspired by the lower bound for the Willmore functional obtained by Li and Yau [LY].

## 2. Preliminaries

Throughout this paper,  $M = M^3$  will be a three-dimensional *Cartan-Hadamard manifold*, i.e., a complete, simply connected Riemannian manifold with nonpositive sectional curvatures. If  $\kappa$  is a nonpositive constant, then  $M^3(\kappa)$  will denote the three-dimensional

Cartan-Hadamard manifold with sectional curvatures equal to  $\kappa$ .  $M(0)$  is the Euclidean space  $\mathbb{R}^3$  and  $M^3(\kappa)$ , for  $\kappa < 0$ , is the hyperbolic space with sectional curvatures equal to  $\kappa$ .

A *proper convex domain* will be the closure of an open convex set or, equivalently, a closed convex set with nonempty interior. For notational simplicity in the setting of relative geometry, let us adopt the following: if  $C \subset M$  then we define  $M_C := M \sim C$ .

For  $C \subset M$ , define the *relative isoperimetric profile* of  $M_C, I_C : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ , by

$$I_C(v) = \inf_D \{ \text{area}(\partial D)_C : D \subset M_C, \partial D \text{ piecewise smooth, } \text{vol}(D) = v \},$$

where  $\text{area}$  is the 2 dimensional Hausdorff measure and  $\text{vol}$  denotes the Riemannian volume in  $M$ . An *isoperimetric region*  $D \subset M_C$  is one for which the equality

$$\text{area}(\partial D)_C = I_C(\text{vol}(D))$$

holds. We remark that isoperimetric regions need not be unique for a given volume. One of the problems in our approach is that isoperimetric regions need not exist in  $M_C$ . We solve this problem by considering isoperimetric regions in bounded sets and letting these sets exhaust  $M_C$ .

Let  $\mathbb{H} \subset M(\kappa)$  be a closed half space. From the reflection argument of the introduction and the isoperimetric inequality in  $M(\kappa)$  we easily obtain that the isoperimetric regions in  $M(\kappa) \sim \mathbb{H}$  are half balls touching orthogonally the boundary of  $M(\kappa) \sim \mathbb{H}$ .

If  $M$  is a three-dimensional Cartan-Hadamard manifold with sectional curvatures  $K_M \leq \kappa$ , then the relative isoperimetric inequality (1.2) in  $M_C$  is equivalent to

$$(2.1) \quad \text{area}(\partial D)_C \geq I_{\mathbb{H}}(\text{vol}(D)),$$

which in turn is equivalent to

$$(2.2) \quad I_C(v) \geq I_{\mathbb{H}}(v),$$

for all  $v > 0$ . We also want to prove that equality holds in (2.1) if and only if  $D$  is a half ball in  $M(\kappa)$ .

Let  $C \subset M$  be a closed set. Denote by  $C_0^1(TM_C)$  the set of  $C^1$  vector fields with compact support in  $M_C$ . For any  $D \subset M_C$  define the *perimeter* of  $D$  relative to  $C$  as

$$\mathcal{P}_C(D) = \sup \left\{ \int_D \text{div } X : X \in C_0^1(TM_C), |X| \leq 1 \right\},$$

where  $|X|$  is the sup norm. If  $\partial D$  is piecewise smooth then  $\mathcal{P}_C(D)$  coincides with  $\text{area}(\partial D)_C$  since the supremum is taken over vector fields with compact support in  $M_C$ , and so the area of  $\partial D \cap \partial C$  does not contribute to the perimeter.

Let  $E$  be the closure of a bounded open set in  $M_C$ . We wish to minimize the perimeter  $\mathcal{P}_C$  amongst sets included in  $E$  subject to a volume constraint, i.e., given  $v \in (0, \text{vol}(E))$ , we want to find  $\Omega_0 \subset E$  such that

$$\mathcal{P}_C(\Omega_0) \leq \mathcal{P}_C(\Omega)$$

for any  $\Omega \subset E$  with  $\text{vol}(\Omega) = \text{vol}(\Omega_0) = v$ . The existence of  $\Omega_0$  is guaranteed by the boundedness of  $E$ ; see [G]. In fact we get

**Lemma 2.1** (Existence and regularity). *Let  $C \subset M^3$  be a proper convex domain with smooth boundary and let  $E$  be the closure of a bounded domain in  $M_C$  with  $(\overline{\partial E})_C$  smooth. Then, for any  $v_0 \in (0, \text{vol}(E))$  there is a set  $\Omega_0 \subset E$  of volume  $v_0$  minimizing the perimeter relative to  $C$ . Moreover:*

- (i) ([GMT])  $\partial\Omega_0$  has constant mean curvature and is smooth in the interior of  $E$ .
- (ii) ([Gr2], p. 263)  $(\overline{\partial\Omega_0})_C$  meets  $\partial C \sim (\overline{\partial E})_C$  orthogonally and it is smooth.
- (iii) ([Wh], [StZ], Thm. 3.6) *If  $(\partial E)_C$  is strictly convex then  $(\partial\Omega_0)_C$  meets  $(\partial E)_C$  tangentially and it is  $C^{1,1}$  in a neighbourhood of  $(\partial E)_C$ .*

**Remark 2.2.** Observe that the above regularity theorem does not apply to points of  $(\overline{\partial\Omega_0})_C \cap \partial C \cap (\overline{\partial E})_C$ .

### 3. The relative isoperimetric inequality in $M^3$

The key method in proving the relative isoperimetric inequality is to obtain a mean curvature comparison in  $M$ . A minor problem in this method is that the boundary of a perimeter-minimizing domain  $\Omega_0$  inside a set  $E$  is only  $C^{1,1}$  (see [Wh], [StZ]). As we shall see later, however, this is not a true problem, since a  $C^{1,1}$  surface is  $C^2$  almost everywhere by Rademacher’s Theorem and a weak divergence theorem still holds for this kind of surfaces. We prove the mean curvature comparison in the following

**Proposition 3.1.** *Let  $M$  be a three-dimensional Cartan-Hadamard manifold with sectional curvatures bounded above by a nonpositive constant  $\kappa$ . Let  $C \subset M$  be a proper convex domain with smooth boundary,  $\Omega \subset M_C$  a domain such that  $\Sigma := (\overline{\partial\Omega})_C$  is a  $C^{1,1}$  surface perpendicular to  $\partial C$  with mean curvature  $H$ , and let  $H_\Sigma := \sup_\Sigma H$ . Then*

$$(3.1) \quad (\kappa + H_\Sigma^2) \text{area}(\Sigma) \geq 2\pi,$$

with equality if and only if  $\Omega$  is isometric to a geodesic half ball in  $M(\kappa)$  of the same volume as  $\Omega$ .

*Proof.* For the proof we shall follow the arguments in [R]. We assume first that  $\Sigma$  is a smooth surface. Consider a family  $\{g_b\}$  of metrics, conformal to the Riemannian metric  $g$  of  $M$ , given by

$$g_b = e^{2u_b} g.$$

The relation between the sectional curvatures of  $g$  and  $g_b$  yields, at every point  $p \in \Sigma$ ,

$$(3.2) \quad e^{2u_b} (K_s)_b = K_s - \left( |\nabla u_b|^2 - \sum_{i=1}^2 (e_i(u_b))^2 \right) - \sum_{i=1}^2 \nabla^2 u_b(e_i, e_i),$$

where  $(K_s)_b$  and  $K_s$  are the sectional curvatures of the tangent plane to  $\Sigma$  for the metrics  $g_b$  and  $g$ , respectively, and  $\{e_i\}$  is a  $g$ -orthonormal basis of the tangent plane to  $\Sigma$ . The gradient and the Hessian of  $u_b$  in  $(M, g)$  have been denoted by  $\nabla u_b$  and  $\nabla^2 u_b$ , respectively.

The surface integral  $\int_{\Sigma} (\lambda_1 - \lambda_2)^2 dA$ , where  $\lambda_i$  are the principal curvatures of  $\Sigma$ , is invariant under conformal changes of the ambient metric. Since

$$(\lambda_1 - \lambda_2)^2 = (\lambda_1 + \lambda_2)^2 - 4\lambda_1\lambda_2 = 4(H^2 + K_s - K),$$

where  $K$  is the intrinsic Gauss curvature of the surface, we have

$$\int_{\Sigma} H^2 dA = \int_{\Sigma} H_b^2 dA_b + \int_{\Sigma} (e^{2u_b}(K_s)_b - K_s) dA + \int_{\Sigma} K dA - \int_{\Sigma} K_b dA_b,$$

where  $H_b, K_b$  are the mean and Gauss curvature of  $\Sigma$  with respect to the metric  $g_b$ , and  $dA, dA_b$  the area forms on  $\Sigma$  induced by  $g, g_b$ , respectively.

Let  $\partial\Sigma$  be the boundary of the surface  $\Sigma$ . Integrating the relation  $\Delta_{\Sigma} u_b = K - K_b e^{2u_b}$  on  $\Sigma$ , where  $\Delta_{\Sigma}$  is the Laplacian for the metric induced on  $\Sigma$  by  $g$ , and applying the divergence theorem we get

$$\int_{\Sigma} K dA - \int_{\Sigma} K_b dA_b = \int_{\Sigma} \Delta_{\Sigma} u_b dA = - \int_{\partial\Sigma} v(u_b) ds,$$

where  $v$  is the inner unit normal to  $\partial\Sigma$  on  $\Sigma$ . So we finally obtain

$$(3.3) \quad \int_{\Sigma} H^2 dA = \int_{\Sigma} H_b^2 dA_b + \int_{\Sigma} (e^{2u_b}(K_s)_b - K_s) dA - \int_{\partial\Sigma} v(u_b) ds.$$

Let us consider first the case  $\kappa = 0$ . Let  $p_0 \in \partial\Sigma \cap \partial C$  and let  $d$  be the distance function to  $p_0$ . For any  $b > 0$  we consider the family of conformal metrics  $g_b = e^{2u_b}g$  given by the functions

$$(3.4) \quad u_b = \log\left(\frac{2b}{1 + b^2 d^2}\right).$$

In case  $M^3 = \mathbb{R}^3$  these metrics are obtained by homothetically blowing up the spherical metric  $(2/(1 + d^2))^2 g$  by a factor of  $b$ .

Equation (3.2) gives in this case, for any  $p \in \Sigma$ ,

$$(3.5) \quad e^{2u_b}(K_s)_b = K_s - \left(\frac{b^2}{1 + b^2 d^2}\right)^2 4d^2 + \left(\frac{b^2}{1 + b^2 d^2}\right)^2 \sum_{i=1}^2 \nabla^2 d^2(e_i, e_i).$$

By the Hessian Comparison Theorem we have  $\nabla^2 d^2 \geq 2$ , so that from (3.5) we get

$$(3.6) \quad e^{2u_b}(K_s)_b \geq K_s + e^{2u_b}.$$

Equality in (3.6) holds if and only if  $\nabla^2 d^2(e_i, e_i) = 2$  along  $\Sigma$ , for  $i = 1, 2$ . By equation (3.3) and inequality (3.6) we obtain

$$(3.7) \quad H_{\Sigma}^2 \text{ area}(\Sigma) \geq \int_{\Sigma} H^2 dA \geq \int_{\Sigma} dA_b - \int_{\partial\Sigma} v(u_b) ds.$$

Let us see that

$$(3.8) \quad \lim_{b \rightarrow \infty} \int_{\Sigma} dA_b = \lim_{b \rightarrow \infty} \int_{\Sigma} e^{2u_b} dA = 2\pi.$$

Let  $r(p) := d(p, p_0)$  be the extrinsic distance to  $p_0$ . Fix  $r_0 > 0$  small. Observe that  $e^{2u_b}$  converges uniformly to 0 in  $\Sigma$  out of the ball  $B(p_0, r_0)$  when  $b \rightarrow \infty$ . For  $r_0$  small enough, the modulus of the gradient of  $r|_{\Sigma}$  over  $\Sigma \cap B(p_0, r_0)$  is approximately 1, and the length of  $\Sigma \cap \partial B(p_0, r)$ , for  $r \in (0, r_0)$ , is approximately  $\pi r$ . By applying the coarea formula to  $r|_{\Sigma}$  we get

$$\int_{\Sigma \cap B(p_0, r_0)} dA_b = \pi \int_0^{r_0} r \left( \frac{2b}{1 + b^2 r^2} \right)^2 dr + o(r_0) = 2\pi + o(r_0),$$

where  $o(r_0)$  converges to 0 when  $r_0 \rightarrow 0$ . Letting  $r_0 \rightarrow 0$  we get (3.8).

On the other hand,  $\partial\Sigma$  is a curve (possibly disconnected) that bounds a region  $R \subset \partial C$ . Recall that  $\nu$ , the inner normal to  $\partial\Sigma$  on  $\Sigma$ , is also the outer normal to  $\partial C$ . As  $p_0 \in \partial C$  we see that a geodesic  $\gamma_p : [0, t_p] \rightarrow M$  from  $p_0$  to any other point  $p \in \partial\Sigma \subset \partial C$  must satisfy  $g(\gamma_p'(t_p), \nu(p)) \geq 0$  by the convexity of  $C$ . Hence  $g(\nabla d, \nu) \geq 0$  for all  $p \in \partial\Sigma$  and we deduce that

$$-v(u_b) = \frac{2b^2 dg(\nabla d, \nu)}{1 + b^2 d^2}$$

is a nonnegative function. Discarding the last summand in (3.7) and taking limits we obtain (3.1).

Let us consider now the equality case

$$(3.9) \quad H_{\Sigma}^2 \text{ area}(\Sigma) = 2\pi.$$

If (3.9) holds then there is also equality in (3.6), which implies that

$$(3.10a) \quad \nabla^2 d^2(v, v) = 2g(v, v), \quad \text{for any } p \in \Sigma, v \in T_p \Sigma.$$

We also have that  $\lim_{b \rightarrow \infty} \int_{\partial\Sigma} (-v(u_b)) ds = 0$  since, after taking limits, there is equality in (3.7).

The sequence  $\{-v(u_b)\}_b$  is pointwise increasing and converges to  $2\nu(d)/d$ . By the Monotone Convergence Theorem

$$0 \leq \int_{\partial\Sigma} \frac{2\nu(d)}{d} ds = \lim_{b \rightarrow \infty} \int_{\partial\Sigma} (-v(u_b)) ds = 0,$$

and so

$$(3.10b) \quad g(\nabla d, \nu) \equiv 0 \quad \text{along } \partial\Sigma.$$

Finally, if (3.9) holds then

$$(3.10c) \quad H_\Sigma = H,$$

so that  $\Sigma$  is a constant mean curvature surface.

Let us see first that (3.10b) implies that  $R$  is totally geodesic. For any  $p \in M$ , define  $\gamma_p : [0, t_p] \rightarrow M$  as the arc-length minimizing geodesic joining  $p_0$  and  $p$ . If  $p \in \partial\Sigma$ , (3.10b) implies that  $\gamma_p$  is tangent to  $\partial C$  at  $p$ . By the convexity of  $C$ , we have that  $\gamma_p([0, t_p]) \subset \partial C$ . So we have  $C_{p_0} := \bigcup_{p \in \partial\Sigma} \gamma_p([0, t_p]) \subset \partial C$ . Hence  $R$ , the closed set in  $\partial C$  bounded by  $\partial\Sigma$ , satisfies

$$R \subset C_{p_0},$$

since the intersection of  $R$  and  $C_{p_0}$  is open and closed in  $R$  and every component of  $R$  intersects  $C_{p_0}$  as  $\partial\Sigma \subset C_{p_0}$ . Observe that when (3.9) holds, (3.10a), (3.10b), (3.10c) are satisfied for any choice of  $p_0 \in \partial\Sigma$  and so  $R \subset C_{p_0}$  for any  $p_0 \in \partial\Sigma$ . Let  $q$  be a point in the interior of  $R$  in  $\partial C$ . Joining  $q$  with three different points  $p_i, i = 1, 2, 3$ , of  $\partial\Sigma$  not lying in the same geodesic, we have  $R \subset C_{p_i}$  for all  $i$ . We get three vectors  $v_i \in T_q\partial C, i = 1, 2, 3$ , pairwise independent, so that  $\sigma(v_i, v_i) = 0, i = 1, 2, 3$ , where  $\sigma$  is the second fundamental form of  $\partial C$ . We conclude that  $\partial C$  is totally geodesic at  $q$  and, hence, over all of  $R$ .

Let us see now that (3.10a) implies that  $\Omega$  is a flat region. With the same notation as in the previous paragraph, let  $p \in \Sigma \sim \partial\Sigma$ . If  $\gamma_p$  is transverse to  $\Sigma$  at  $p$  then  $\nabla^2 d^2 = 2g$  at  $p$  and, by the standard comparison theorems in Riemannian Geometry,  $\nabla^2 d^2 \equiv 2g$  along  $\gamma_p([0, t_p])$ . Let  $U$  be an open neighbourhood of  $p$  in  $\Sigma \sim \partial\Sigma$  so that  $\gamma_q$  is transverse to  $\Sigma$  at  $q$  for every  $q \in U$ . Then on the cone  $\bigcup_{q \in U} \gamma_q([0, t_q])$  we have  $\nabla^2 d^2 \equiv 2g$ , so this cone is flat.

On the other hand, the set of unit vectors  $v \in T_{p_0}M$  for which there is  $p \in \Sigma \sim \partial\Sigma$  with  $\gamma'_p(0) = v$  and  $\gamma_p$  does not meet  $\Sigma$  transversally at  $p$ , has measure zero on the unit sphere  $S_{p_0} \subset T_{p_0}M$ . This can be easily seen by considering the smooth map  $\Sigma \sim \partial\Sigma \rightarrow S_{p_0}$  given by  $p \mapsto \gamma'_p(0)$ , whose critical points are precisely the points  $p \in \Sigma \sim \partial\Sigma$  for which  $\gamma_p$  is not transverse to  $\Sigma$  at  $p$ , and by applying Sard's Theorem. We conclude that the set of points in  $\bigcup_{p \in \Sigma \sim \partial\Sigma} \gamma_p([0, t_p])$  where the metric is flat is dense, and so  $\bigcup_{p \in \Sigma} \gamma_p([0, t_p])$  is flat. Since  $\Omega \subset \bigcup_{p \in \Sigma} \gamma_p([0, t_p])$ , we conclude that  $\Omega$  is flat.

Finally, let us consider (3.10c). Since  $\Omega$  is flat,  $R$  is totally geodesic, and  $H = H_\Sigma > 0$ , we can apply the theorem by S. Montiel and A. Ros [MoR] which implies, for regions of this type, that

$$3 \text{ vol}(\Omega) \leq \frac{1}{H} \text{ area}(\Sigma),$$

with equality if and only if  $\Omega$  is a half-ball in Euclidean space. But on  $\Sigma$  we have

$$(3.11) \quad \Delta_\Sigma d^2 = 4 + 4Hd\langle \nabla d, N \rangle,$$

where  $N$  is the unit normal to  $\Sigma$  in the direction of the mean curvature vector of  $\Sigma$ . Integrating (3.11) on  $\Sigma$ , we obtain the classical Minkowski formula

$$3 \operatorname{vol}(\Omega) = \frac{1}{H} \operatorname{area}(\Sigma).$$

This concludes the proof in the Euclidean case.

Let us consider now the hyperbolic case. By scaling the metric  $g$  of  $M$  we may assume that  $\kappa = -1$ , so that the inequality we intend to prove is

$$(3.12) \quad (-1 + H_\Sigma^2) \operatorname{area}(\Sigma) \geq 2\pi,$$

with equality if and only if  $\Omega$  is a half-ball in the hyperbolic space  $M^3(-1)$  of constant sectional curvature equal to  $-1$ .

Consider again a point  $p_0 \in \partial\Sigma$  and let  $d$  be the distance to  $p_0$ . We define the family of conformal metrics  $g_b = e^{2u_b}g$ , given by the functions

$$(3.13) \quad u_b = \log\left(\frac{2b}{(1 - b^2) + (1 + b^2) \cosh(d)}\right), \quad b > 1.$$

When  $M$  is the three-dimensional hyperbolic space, this family of metrics is obtained by homothetically expanding the spherical metric

$$\left(\frac{1 - \tanh^2(d/2)}{1 + \tanh^2(d/2)}\right)^2 g.$$

From (3.2) we obtain the following relation for the sectional curvatures of the tangent plane to  $\Sigma$ .

$$(3.14) \quad e^{2u_b}(K_s)_b = K_s + 1 + e^{2u_b} + \left(\frac{1 + b^2}{(1 - b^2) + (1 + b^2) \cosh(d)}\right) \times \left(\sum_{i=1}^2 \nabla^2 \cosh(d)(e_i, e_i) - 2 \cosh(d)\right),$$

where  $\{e_1, e_2\}$  is a  $g$ -orthonormal basis of the tangent plane to  $\Sigma$ . By the Hessian Comparison Theorem we know that  $\nabla^2 \cosh(d) \geq \cosh(d)g$ . So we obtain

$$(3.15) \quad e^{2u_b}(K_s)_b \geq K_s + e^{2u_b} + 1.$$

Equality holds in (3.15) if and only if  $\nabla^2 \cosh(d)(e_i, e_i) = \cosh(d)$  for  $i = 1, 2$ . From equation (3.3) and inequality (3.15) we obtain

$$\int_{\Sigma} (-1 + H^2) dA \geq \int_{\Sigma} dA_b - \int_{\partial\Sigma} v(u_b) ds.$$

As in the previous case one shows that  $\lim_{b \rightarrow \infty} \int_{\Sigma} dA_b \rightarrow 2\pi$  and, by the convexity of  $C$ , that  $-v(u_b) \geq 0$ , which yields the desired estimate (3.12).

If equality holds in (3.12) then we conclude, as in the Euclidean case, that  $\nabla^2 \cosh(d)(v, v) = \cosh(d)$  for any unit tangent vector  $v$  to  $\Sigma$  at any point of  $\Sigma$ , that  $H$  is constant, and that  $g(\nabla d, v) = 0$  at any point of  $\partial\Sigma$ .

Condition  $\nabla^2 \cosh(d)(v, v) = \cosh(d)$  for any unit tangent vector  $v$  to  $\Sigma$  at any point of  $\Sigma$  implies, by the standard comparison theorems, that the metric  $g$  of  $\Omega$  (i.e., on the cone over  $\Sigma$  with vertex  $p_0$ ), has constant sectional curvatures equal to  $-1$ . Moreover, condition  $g(\nabla d, v) = 0$  at any point of  $\partial\Sigma$  implies that  $R$  is a totally geodesic surface. Finally, as  $\Sigma$  has constant mean curvature  $H > 1$ , we see as in [Mo], Theorem 9, by taking inner parallels, that

$$\int_{\Sigma} (\cosh(d) + H \sinh(d) \langle \nabla d, N \rangle) dA \geq 0, \quad N \perp \Sigma$$

with equality if and only if  $\Omega$  is a half ball in hyperbolic space. But since the metric of  $\Omega$  is hyperbolic, we have  $\nabla^2 \cosh(d) = \cosh(d)g$  in  $\Omega$  so that integrating

$$\Delta_{\Sigma} \cosh(d) = 2 \cosh(d) + 2H \sinh(d) \langle \nabla d, N \rangle$$

on  $\Sigma$  we get

$$\int_{\Sigma} (\cosh(d) + H \sinh(d) \langle \nabla d, N \rangle) dA = 0.$$

This completes the proof in the hyperbolic case  $\kappa = -1$ .

Finally, if  $\Sigma$  is merely  $C^{1,1}$ , the arguments in the proof apply without changes since the principal curvatures of  $\Sigma$ , and hence the mean and the Gauss curvature, are defined almost everywhere. The divergence theorem still holds under our weak hypothesis.  $\square$

By using the mean comparison result in Proposition 3.1 we can now prove the isoperimetric comparison theorem.

**Theorem 3.2.** *Let  $M$  be a three-dimensional Cartan-Hadamard manifold with sectional curvatures bounded above by a nonpositive constant  $\kappa$ , and let  $M(\kappa)$  be the three-dimensional Cartan-Hadamard manifold with constant sectional curvatures equal to  $\kappa$ . Assume that  $C \subset M$  is a proper convex domain with smooth boundary and that  $\mathbb{H} \subset M(\kappa)$  is a half space. Then we have*

$$(3.16) \quad I_C \geq I_{\mathbb{H}},$$

which in turn implies that for any bounded finite perimeter set  $D \subset M_C$  we have

$$(3.17) \quad \text{area}(\partial D)_C \geq I_{\mathbb{H}}(\text{vol}(D)).$$

Moreover, equality holds in (3.17) if and only if  $D$  is isometric to a half ball in  $M(\kappa)$ .

*Proof.* Since the existence of isoperimetric regions is a crucial point of our arguments, but it is not guaranteed in the noncompact  $M_C$ , we first construct an exhaustion of  $M_C$  by relatively compact sets  $\{E_k\}_{k \in \mathbb{N}}$ . We take  $p_0 \in \partial C$ , and define  $E_k = \bar{B}(p_0, r_k)_C$ , where  $r_k$  is an increasing diverging sequence of positive numbers, and  $\bar{B}(p_0, r_k)$  is the closed ball centered at  $p_0$  of radius  $r_k$ .

Since  $E_k$  is bounded, isoperimetric regions exist on  $E_k$  for any given volume  $v \in (0, \text{vol } E_k)$ . The boundary  $\Sigma$  of any isoperimetric region  $\Omega$  in  $\overline{E_k}$  satisfies the regularity properties of [Lemma 2.1](#) provided there is no point in  $\Sigma \cap \partial C \cap (\overline{\partial E_k})_C$ . Assume there is  $q_0 \in \Sigma \cap \partial C \cap (\overline{\partial E_k})_C$ . The set  $\partial E_k$  is contained in the geodesic sphere  $\partial B(p_0, r_k)$ , which meets  $\partial C$  at  $q_0$  at an angle less than or equal to  $\pi/2$ . Reflecting locally  $\Omega$  with respect to  $\partial C$  and blowing up  $\Omega$  and the metric from  $q_0$ , [Gr1], we obtain a cone in  $\mathbb{R}^3$  which is area minimizing in a wedge of  $\mathbb{R}^3$ . This implies regularity if the angle is  $\pi/2$  and it is not possible if the angle is less than  $\pi/2$ ; see [G], Thm. 15.5.

Fix  $k \in \mathbb{N}$  and assume that  $\Omega_k$  is an isoperimetric region in  $E_k$ . The set  $\Omega_k$  may have several components. Let  $\Omega_k = \Omega_k^1 \cup \Omega_k^2$ , where  $\Omega_k^1$  consists of the components of  $\Omega_k$  touching  $\partial C$  (in an orthogonal way), and  $\Omega_k^2$  consists of the components of  $\Omega_k$  disjoint from  $\partial C$ . Then by (3.1)

$$(\kappa + H_{(\partial\Omega_k^1)_C}^2) \text{area}(\partial\Omega_k^1)_C \geq 2\pi[\#\{\text{components of } \Omega_k^1\}] \geq 2\pi.$$

On the other hand, by [Kl] or [R],

$$(\kappa + H_{(\partial\Omega_k^2)_C}^2) \text{area}(\partial\Omega_k^2)_C \geq 4\pi[\#\{\text{components of } \Omega_k^2\}] \geq 0.$$

Adding both inequalities we get

$$(\kappa + H_{(\partial\Omega_k)_C}^2) \text{area}(\partial\Omega_k)_C \geq 2\pi,$$

and hence

$$(3.18) \quad H_{(\partial\Omega_k)_C} \geq H_\kappa(\text{area}(\partial\Omega_k)_C),$$

where  $H_\kappa(a)$  denotes the mean curvature of a geodesic sphere of area  $2a$  in  $M(\kappa)$ . By Proposition 3.1, equality holds in (3.18) if and only if  $\Omega_k$  is isometric to a geodesic half ball in  $M(\kappa)$ .

Denote by  $I_k$  the isoperimetric profile of  $E_k$ . By standard arguments, [Hs], pp. 170–172, we have

- $I_k$  is continuous and increasing,
- when  $I_k$  is smooth at  $v_0$  then  $I'_k(v_0) = 2H$ , where  $H$  is the constant mean curvature in the interior of  $E_k$  of any isoperimetric region of volume  $v_0$ , and
- left and right derivatives of  $I_k$  exist everywhere.

Since  $I_k$  is a continuous monotone function with left and right derivatives at every point, it is absolutely continuous.

The continuity of  $I_k$  follows from the convergence of isoperimetric regions. To prove the monotonicity of  $I_k$  we just need to show that the constant mean curvature  $H$  of the boundary of an isoperimetric region  $\Omega$  in the interior of  $E_k$  is positive. Let  $\Sigma = \partial\Omega_C$ . If  $\Sigma$  does not touch  $(\partial E_k)_C$  then there is an outer parallel  $\partial C_t$  to  $\partial C$ , which is tangent to  $\Sigma$  at

some point and leaves  $\Sigma$  on one side. Standard comparison theorems show that the principal curvatures of  $\partial C_t$  are nonnegative. By the maximum principle,  $H \geq 0$ . But in case  $H = 0$ , we obtain from the maximum principle that  $\Sigma$  and  $\partial C_t$  locally coincide and, by a connectedness argument, that a connected component of  $\Sigma$  is contained in  $\partial C_t$ , which gives us a contradiction. If  $\Sigma \cap (\partial E_k)_C$  is not empty then the maximum principle shows that  $H$  is larger than or equal to the mean curvature of  $(\partial E_k)_C$  at some point, which is strictly positive since geodesic spheres in a Cartan-Hadamard manifold are strictly convex.

The computation of the derivative  $I'_k(v_0)$  is standard by making a variation supported around a point of  $\Sigma \cap \text{int}(E_k)$ . The fact that left and right derivatives always exist follows from the convergence of isoperimetric regions of volumes  $v_k \rightarrow v_0$  to an isoperimetric region of volume  $v_0$ , see [HS], p. 171.

Let  $J_k$  be the restriction of the isoperimetric profile of  $M(\kappa)$  to the interval  $(0, \text{vol } E_k)$ . Let  $f(a), g(a)$  be the inverse functions of  $I_k, J_k$ , respectively. We know that  $g'(a) = J'_k(a)^{-1} = (2H_\kappa(a))^{-1}$ , and that, when  $f'$  exists,  $f'(a) = I'_k(a)^{-1} = (2H)^{-1}$ , where  $H$  is the mean curvature in the interior of  $E_k$  of any isoperimetric region of volume  $f(a)$ . By Proposition 3.1, we obtain  $g'(a) \geq f'(a)$  a.e. Since  $f$  is absolutely continuous (and  $g$  is smooth), we have  $g(a) \geq f(a)$ . It follows that  $I_k \geq J_k$ .

If equality holds for some  $v_0$ , then for  $a_0 = J_k(v_0) = I_k(v_0)$  we have  $g(a_0) = f(a_0)$ . Since  $g' \geq f'$  we obtain that  $f \equiv g$  in the interval  $(0, a_0)$  and so  $H_\kappa(a_0)^{-1} = H(a_0)^{-1}$ . If  $\Omega_0$  is any isoperimetric region of volume  $v_0$  then Proposition 3.1 implies that  $\Omega_0$  is isometric to a half ball in  $M(\kappa)$  of volume  $v_0$ .

Finally let  $\Omega \subset M_C$  be relatively compact with smooth boundary. Then  $\Omega \subset E_k$  for some  $k$ , and

$$\mathcal{P}(\Omega) \geq I_k(\text{vol}(\Omega)) \geq I_{\mathbb{H}}(\text{vol}(\Omega)).$$

If equality holds then  $\Omega$  is an isoperimetric region in  $E_k$  and  $I_k(\text{vol}(\Omega)) = I_{\mathbb{H}}(\text{vol}(\Omega))$ . By the discussion in the above paragraph we have that  $\Omega$  is isometric to a half ball in  $M(\kappa)$  of volume  $\text{vol}(\Omega)$ .  $\square$

**Corollary 3.3.** *Suppose that  $M$  is a three-dimensional Cartan-Hadamard manifold,  $C \subset M$  a proper convex domain with smooth boundary, and  $D$  bounded and of finite perimeter in  $M \sim C$ . Then*

$$\text{area}(\partial D \sim \partial C)^3 \geq 18\pi \text{vol}(D)^2,$$

*and equality holds if and only if  $D$  is a flat half ball.*

#### 4. The relative isoperimetric inequality for a general convex set

In this section,  $C$  will denote a bounded strictly convex body in  $\mathbb{R}^3$ . No assumption on the regularity of its boundary is made. We say that a convex body is *strictly convex* if its boundary does not contain a nontrivial segment [Sch], p. 77. Recall that  $p$  is an *extreme point* of  $C$  if it cannot be written in the form  $p = \lambda x + (1 - \lambda)y$ , with  $x, y \in C, x \neq y$ , and

$\lambda \in (0, 1)$ . Any point in the boundary of a strictly convex set is an extreme point. A *cap of  $C$  around  $p$*  is a set of the form  $C \cap H^+$ , where  $H^+$  is a closed half space with  $p \in \text{int } H^+$ , [Sch], pp. 18–19.

For strictly convex sets we have the following result:

**Theorem 4.1.** *Let  $C \subset \mathbb{R}^3$  be a proper convex domain which is strictly convex, and  $\mathbb{H} \subset \mathbb{R}^3$  a half space. Then, for any  $v > 0$ ,*

$$I_C(v) > I_{\mathbb{H}}(v).$$

*That is, equality never holds in the above inequality for these convex bodies.*

*Proof.* Using standard results on the Hausdorff metric, we can find a sequence of convex bodies with smooth boundary  $C_k \subset \mathbb{R}^3$ , with  $C \subset C_k$  for all  $n \in \mathbb{N}$ , converging in the Hausdorff distance to  $C$ . Let  $\Omega \subset (\mathbb{R}^3)_C$  be a relatively compact set and define  $\Omega_k = \Omega \cap (\mathbb{R}^3)_{C_k}$ . Then  $\text{vol}(\Omega_k) \rightarrow \text{vol}(\Omega)$  and  $\mathcal{P}_C(\Omega) \geq \mathcal{P}_{C_k}(\Omega_k)$ . Since the relative isoperimetric inequality (2.1) is satisfied in  $(\mathbb{R}^3)_{C_k}$ , we have  $\mathcal{P}_C(\Omega) \geq \mathcal{P}_{C_k}(\Omega_k) \geq I_{\mathbb{H}}(\text{vol}(\Omega_k))$ . Taking limits, we get  $\mathcal{P}_C(\Omega) \geq I_{\mathbb{H}}(\text{vol}(\Omega))$ , and the isoperimetric inequality  $I_C(v) \geq I_{\mathbb{H}}(v)$  holds in  $(\mathbb{R}^3)_C$ .

To see that this inequality is always strict, consider a region  $\Omega \subset (\mathbb{R}^3)_C$  such that equality  $\mathcal{P}_C(\Omega) = I_{\mathbb{H}}(\text{vol}(\Omega))$  holds. Let  $p$  be a point in the interior, relative to  $\partial C$ , of  $\partial\Omega \cap \partial C$ . The strict convexity implies that  $p$  is an extreme point of  $C$ . By [Sch], Lemma 1.4.6, there is a cap  $P^+$  of  $C$  around  $p$  contained in the interior of  $\partial\Omega \cap \partial C$ . Let  $P^-$  be the half space obtained as the closure of the complement of the half space determining  $P^+$ . Consider the convex set  $C' = C \cap P^-$ , and  $\Omega' = \Omega \cup (C \cap P^+)$ . We have  $\mathcal{P}_{C'}(\Omega') = \mathcal{P}_C(\Omega)$ , and  $\text{vol}(\Omega) < \text{vol}(\Omega')$ . Hence

$$\mathcal{P}_{C'}(\Omega') = \mathcal{P}_C(\Omega) = I_{\mathbb{H}}(\text{vol}(\Omega)) < I_{\mathbb{H}}(\text{vol}(\Omega')),$$

and so  $I_C(\text{vol}(\Omega')) < I_{\mathbb{H}}(\text{vol}(\Omega'))$ . This is a contradiction, since we have already proved that in  $(\mathbb{R}^3)_{C'}$  the isoperimetric inequality  $I_C(v) \geq I_{\mathbb{H}}(v)$  holds.  $\square$

**Remark 4.2.** The first paragraph in the proof of Theorem 4.1 shows that the isoperimetric inequality  $\text{area}(\partial D \sim \partial C)^3 \geq 18\pi \text{vol}(D)^2$  holds for any region  $D$  outside a convex set  $C$  with nonsmooth boundary in  $\mathbb{R}^3$ . The authors have not characterized what happens in the equality case, and they believe that techniques different from the ones used in this paper should be employed.

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